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# Your One-Stop Robot Building Partner

AGV Body · Motion · Perception · Energy · Vehicle Control · Other Components





# **About**

### **ATOMBOTIX**

Serviced

Mobile Robot **Models Built** 

**OEM Clients** Served

ATOMBOTIX—born from "Atom" and "Robotics" —delivers the fundamental building blocks for modern automation.

We believe every robot should be assembled from precise, standardized components—just as atoms combine to form molecules—enabling limitless combinations tailored to any application.

Founded by engineers from Oxford and Huazhong University, and shaped by experience at the world's top robotics companies, we bring deep technical rigor and a global perspective to the modular robotics space.

Our mission is to unlock scalable, flexible automation by redefining how mobile robots are built—from the ground up.



### **Core Business**

• ATOMBOTIX specializes in the design, development and sourcing of modular mobile robot building solutions, utilizing global supply chain, striving to help mobile robot OEMs to build their solution effortlessly & cost effectively

Our systems are engineered for seamless integration into a wide variety of mobile robotics platforms—enabling OEMs and integrators to build, adapt, and scale with unmatched efficiency.

Each solution is built on our standardized core units, including the AGV Body, Motion, and Energy modules. These components support rapid prototyping, easy customization, and scalable integration into existing workflows—dramatically accelerating the path from concept to implementation.





### WHY CHOOSE US?



**One-Stop Service:** From motors, sensors, controllers to batteries and navigation modules paired with customization and integration services. By one-stop procurement and technical integration, we reduce downtime, accelerate deployment, and optimize lifecycle costs for AGV/AMR solutions.



**Customized Solutions:** Offering end-to-end tailored services-from hardware configuration and software algorithms to scenario implementation-based on clients' industry attributes and production needs.



**Technological Innovation:** Integrating cutting-edge Al and IoT technologies to achieve precise control and adaptive optimization of robotic systems.



**Cost-Efficient Automation:** Our AGV and AMR solutions are designed to reduce operational costs through automation of material handling, warehouse sorting, and production logistics. By minimizing labor dependency and improving resource utilization, we help clients achieve significant long-term savings.









**AGV Body** 



#### Platform Style

Platform Lifter 600kg/1000kg/1500kg

#### Stacker Truck

Compact Stacker 1.4T/2.0T/3.0T

Counter Balance 1.5T/Outdoor Counter Balance 3.5T

Omni-Stacker 1T

Reach Stacker 1.4T/2.0T

#### Pallet Truck

Bottom Pallet Truck 1.0T/1.6T/2.0T

#### Tugger

Heavy Duty Tugger 3.0T/5.0T

02. Motion



#### Steering Wheel Module

AB-SW-Customized Model

AB-DDS-Customized Model

AB-iDW-Customized Model

AB-DW-Customized Model

AB-HW-Customized Model

#### Servo Motor

DC Servo Motor/Servo Drive

#### Caster Wheel

AGV Driving Wheel/AGV Universal Wheel

#### Mecanum Wheel

Mecanum Wheel

#### Lifting and Rotating Mechanism

AB-LRP-Customized Model

#### **Planetary Gearbox**

AB-PGT-Customized Model

03. Energy



#### **Contact Charging**

NPB-1200

Manual Charger-1200W

CC-Compact Charger

SCC-Split-type Compact Charger

#### Wireless Charging Series

Wireless Charging 24&48 V

#### Lithium-ion Battery

Modular Lithium-ion Battery

Customized Battery-LFP 24V&48V

Low-temp. Battery

#### DC-DC

DC-DC Enclosed 200W

DC-DC DIN-Rail 240W

#### Brush Plate

Brush Plate

**04.** Perception



#### 2D Lidar Series

2D NAVI PRO/MINI NAVIMINI NAVI PRO/Ranger/Ranger

#### **3D Lidar Series**

3D Ranger/Ranger Slim

Mini Navi/Mini Navi Pro

Ranger/Ranger Pro

#### Camera

Object Finder-HD

Object Finder-iTof

#### **QR Scanning Camera**

QR Navigator

# **PRODUCT CATALOG**

#### **ATOMBOTIX**

**04.** Perception



#### RFID

AB-RFID-1S/AB-RFID-1SN

#### Magnetic

AB-MGS-080N /AB-MGS-160N /AB-MGS-160ND

Magnetic Sensor Bar-16&32&48&64

05. Vehicle Control



#### IPC

AB-MC-IPC-M20-I5/I7

**Of.** Other Components



#### Audio

AB-AD100-3W/5W

#### Bumper

AB-BS-Customized/RC-Lxxx

#### **LED**

AB\_LED01/AB-Layer Lamp/3 Color Lamp/Stroboscopic Lamp/Acousto-optic Lamp

#### **Warning Light**

Warning Light Series

#### Network

TL-CPET300L

# **Solution:**



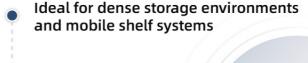




### Platform lifting type AGV Body **Product Introduction**

Latent-type AGV bodies are low-profile, high-maneuverability platforms designed to operate beneath racks, shelves, or trolleys. They are ideal for high-throughput material handling in warehouses and automated storage

These AGV bodies form the base of shelf-carrying AGVs commonly used in goods-to-person systems and smart intralogistics.



Modular architecture supports rapid development

Easily adaptable to different load

forms and rack interfaces

Designed for 24/7 operation with minimal maintenance

### Our product portfolio covers two main categories:

We offer a full range of AGV bodies that serve as the structural foundation for various automated guided vehicles.

Each AGV body is built for durability, precision, and easy integration with navigation systems, lifting mechanisms, and

control units. We offer modular interface designs, standardized mounting points, and tailored dimensions to support

rapid deployment and system compatibility. Whether your application is warehouse automation, production logistics, or

smart factory operations, our AGV bodies offer a reliable and flexible starting point for building high-performance AGVs.

Designed for OEMs and system integrators, our bodies are robust, modular, and easy to customize.

General Introduction

**AGV BODY** 



Platform lifting type AGV body designed for underride shelf-carrying operations



Forklift-type AGV body designed for underride shelf-carrying operations

#### **Key Features:**

Advantages:

Ultra-low chassis height ————————————————————————————————————	(as low as 180 mm)
Precision positioning for docking and lifting	
Preconfigured for lifting modules ————————————————————————————————————	<ul> <li>(scissor, roller, or lifter platforms)</li> </ul>
Reserved slots for navigation sensors	(QR code, SLAM, vision)
Lightweight yet high-strength structure for speed and stability	

Latent body can be integrated into systems for e-commerce, automotive part handling, electronics manufacturing, and more.

### Forklift-type AGV Body

Product Introduction



Forklift-style AGV body are designed for applications that require lifting, stacking, or towing. These bodies serve as the chassis for AGVs that mimic traditional forklifts or towing vehicles but operate autonomously in industrial environments.

We offer several subtypes based on usage:

Stacker-type bodies, compatible with vertical masts for high-rack access

Pallet-type bodies, optimized for low-lift pallet transport

Towing-type bodies, with connection points for trailers or carts

#### **Benefits:**



Suitable for indoor and semi-industrial environments

Reduces mechanical development costs for integrators

#### **Key Features:**

- ▶ Heavy-duty welded frames and high structural rigidity
- Reserved installation areas for lifting columns, forks, sensors, and controllers
- Integrated cable channels and electrical interface kits
- Doptional bumpers, casters, and side panels for safety and stability

These AGV bodies are widely used in warehouse logistics, manufacturing lines, and material handling systems where automated vertical lifting or towing is required.

Platform lifting type AGV body







Туре		Platform Style	
Model	AB-FLB-PL06	AB-FLB-PL10	AB-FLB-PL15
Feature			
Kinematics Model	D	oifferential drive of two Wheels	
Self Weight (Including Battery)	130 kg	180 kg	200 kg
Rated Load Capacity	600 kg	1000 Kg	1500 kg
Dimensions	950 × 650 × 250 mm	1150 × 820 × 260 (±5) mm	1150 × 820 × 260 mm
Rotation Diameter	963 mm	1199 mm	1199 mm
Chassis Ground Clearance	303 IIIII	25 mm	119911111
Lifting Panel Size	850 × 600 mm	1030 × 770 mm	1030 × 770 mm
Lifting Height	830 × 000 111111	60 mm	1030 × 770 11111
Basic Dimensions		00 111111	
Rated Operating Speed,			
Rated load/No Load	1.5 m/s; 1.9 m/s	1.5 m/s; 2.0 m/s	1.5 m/s; 1.7 m/s
Acceleration, Rated load/No Load	0.3 m/s <sup>2</sup> ; 0.6 m/s <sup>2</sup>	0.3 m/s <sup>2</sup> ; 0.6 m/s <sup>2</sup>	0.3 m/s <sup>2</sup> ; 0.6 m/s <sup>2</sup>
Rotation Speed, Rated load/No Load	100°/s; 200°/s	60 °/s; 100 °/s	30 °/s; 60 °/s
Motion			
Drive Motor Power	1.0 (0.5 × 2) kW	2.1 (1.05 × 2) KW	2.1 (1.05 × 2) KW
Power of Lifting Motor	400 w	750 w	750 w
Power of Rotation Motor	750 w	400 W	750 w
Drive Motor Type		Integrated Servo Wheel	
Motor Controller Communication		CAN/RS485	
Energy			
Battery Type		Lithium Iron Phosphate	
Capacity/Rated Voltage	48 V / 24 Ah	48 V /40 Ah	48 V /50 Ah
Charge-Discharge Cycle Times		1,500 times	
Rated Working Condition			
Endurance Time		8 h	
Charging Time After		-2.5.h	
Complete Discharge		≤1.5 h	
BMS Communication Protocol		CAN/RS485	
Others			
Human-Computer		Taylah Sarran	
Interaction Mode		Touch Screen	
Front Laser Obstacle Avoidance (Quantity/Installation Height)	1 Piece/201.5 mm	1 piece/198.5 mm	1 piece/198.5 mm
3D Vision Obstacle Avoidance/ Rear Ultrasonic		Optional	
E-Stop Buttons/Bumper	Included	2 pieces (1	front, 1 rear)
Pressure Sensor		Chandand	,
Acoustic-Optic Alarm		Standard	
Chassis Damping Mode	50/ /2 00	Two-stage Floating Chassis	/20
Climbing Capacity	≤5%/2.8°	≤5%	1/3°
Step Capacity		≤5 mm	
Gutter Crossing Capacity		≤30 mm	5.0511.)
Communication		pports dual-band Wi-Fi (2.4GHz &	,
Humidity		ve Humidity: 10%–90% (without co	
Temperature	Working Area: -10°C-45°C		a: -10°C-40°C
	Charging Area: 0°C-45°C	Charging Ai	rea: 0°C-40°C

Note: Customization available on request.

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Туре					er Truck				
Model	AB-FLB-CS14(24V)	AB-FLB-CS14(48V)	AB-FLB-CS20	AB-FLB-CS30	AB-FLB-OS10	AB-FLB-RS14	AB-FLB-RS20 II	AB-FLB-RS20 III	AB-FLB-CB35-Outdoo
Feature									
Compatible Navigation				2D&3D SLAN	//VSLAM/Natural Feature/R	TK/Laser Reflector			
Kinematic Model					Single Steering Wheel				
Rated Load Capacity	1400 k	kg	2000 kg	3000 kg	1000 kg	1400 kg	20	00 kg	3500 kg
Lifting Height	1600 m	nm	3000 mm	3000 mm	1600 mm	1600 mm	50	0 mm	3300 mm
Self Weight (Including Battery)	680 kg	g	1200 kg	1860 kg	770 kg	1890 kg	/	/	5380 kg
Basic Dimensions									
Overall Dimensions (l×w×h)	1637 × 985	× 2035	1896 × 1121 × 2235	2073 × 1348 × 2500	1644 × 980 × 2035	1881 × 1184 × 2120	2197 × 1161 × 2180	2287 × 1161 × 2180	3510× (1300/1200) ×21
Fork Size (l/e/s)	1150/180/	55 mm	1150/180/75 mm	1150/240/70 mm	1150/210/60 mm	1050/120/40 mm	1150/1	80/55 mm	1070/125/50 mm
Fork Outer Width	680 mm (Customiz	zation Optional)	680 mm	680 mm	680 mm	620 mm	680 mm		1100 mm
Min. Turning Radius (Wa)	1180 m	nm	1440 mm	1750 mm	1433 mm	1481 mm	1736 mm	1826 mm	2025 mm
Min. Right Angle Stacking Aisle Width	1800 mm + Saf	fety Margin	2060 mm + Safety Margin	/	1644 mm + Safety Margin	2033 mm + Safety Margir	2355 mm + Safety Margi	2455 mm + Safety Marg	gin /
Driving Speed,Full load/Empty Load	5/5 km	ı/h	5/5 km/h	5/6 km/h	5/5 km/h	5/5 km/h	5/5	km/h	15/15 km/h
Lifting Speed,Full Load/Empty Load	115/170 r	mm/s	90/120 mm/s	115/170 mm/s	115/170 mm/s	115/170 mm/s	90/12	20 mm/s	/
Descent Speed,Full load/Empty load	160/125 r	mm/s	120/110 mm/s	160/125 mm/s	160/125 mm/s	114/114 mm/s	120/1	10 mm/s	/
Climbing Performance,Full Load/Empty Load	3%/59	%	3%/5%	3%/5%	3%/5%	3%/5%	59	6/8%	14% / 15%
Driving Brake Mode					Electromagnetic Braking				
Motion									
Drive Motor Power	1.25 kW	1.5 kW	1.5 kW	2.2 kW	1.5 kW	2.2 kW	1.	5 kW	AC 6×2 kW
Drive Motor Type					Asynchronous AC Motor				
Steering Motor Type					48 V DC servo motor				
Lifting Mechanism					Hydraulic Control				
Motor Controller Communication					CAN/RS485				
Energy									
Battery Type					Lithium Iron Phosphate				
Battery Voltage/Rated Capacity	24 V / 210Ah	48 V / 105 Ah	48 V / 210 Ah	48 V / 210 Ah	48 V / 105 Ah	24 V / 210 Ah	24 V	/ 210Ah	80 V / 460 Ah
BMS Communication Protocol					CAN/RS485				
Charging Type					Contact Charging				
Charging Speed					< 2h				
Perception									
Navigation Sensor					Bracket Included				
Object Detection Lidar					Optional				
Encoders					Optional				
Fork Tip Sensor					Bracket Included				
Pallet Detection Camera					Space Included				
Bumper Pressure Sensor					Included				
Others									
Communication				D	ual-band Wi-Fi (2.4GHz & 5.0	OGHz)			
HMI					7 Inch HMI Included				
Speaker/Light Beam/E-Stop Buttons/Status Light					Included				
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Note: Customization available on request.

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		Pallet Truck		Tugger	
Model	AB-FLB-PT10	AB-FLB-PT16	AB-FLB-PT20	AB-FLB-TG30	AB-FLB-TG50
Feature					
Compatible Navigation		2D8	3D SLAM/VSLAM/Natural Feature/RTK/Laser Re	eflector	
Kinematic Model			Single Steering Wheel		
Rated Load Capacity	1000 kg	1600 kg	2000 kg	3000 kg	5000 kg
Lifting Height	200 mm	120 mm	180 mm	/	/
Self Weight (Including Battery)	230 kg	450 kg	520 kg	/	/
Basic Dimensions					
Overall Dimensions (l×w×h)	1464 × 851 × 564	1710 × 870 × 1900	1832 × 873 × 2035	1720 × 1060 × 1966.5	1720 × 1060 × 1966.5
Fork Size (l/e/s)	1120/185/65 mm	60/173/1220 mm	1200/160/70 mm	/	/
Fork Outer Width	680 mm	540/680 mm	660 mm	/	/
Min. Turning Radius (Wa)	979 mm	1260 mm	1428 mm	1422 mm	1422 mm
Min. Right Angle Stacking Aisle Width	1581 mm + Safety Margin	/	1930 mm + Safety Margin	/	/
Driving Speed,Full load/Empty Load	4/5 km/h	4.5/5.4 km/h	5/5 km/h	5/6 km/h	5/6 km/h
Lifting Speed, Full Load/Empty Load	26/26 mm/s	30/48 mm/s	30/35 mm/s	600	1000
Descent Speed, Full load/Empty load	26/26 mm/s	40/28 mm/s	42/30 mm/s	2400	3200
Climbing Performance, Full Load/Empty Load	3%/3%	6%/8%	3%/5%	5%/8%	5%/8%
Driving Brake Mode	Motor Reverse Braking	Electroma	gnetic Braking	Electromagnetic Braking	Electromagnetic Braking
Motion					
Drive Motor Power	0.8 (0.4 × 2) kW	1 kW	1.25 kW	2.2 kW	3 kW
Drive Motor Type		24 V Asynchronous AC motor		24 V Asynchro	onous AC motor
Steering Motor Type		48 V DC servo motor		48 V DC s	ervo motor
Lifting Mechanism		48 V DC Servo			/
Motor Controller Communication		CAN/RS485		CAN/	/RS485
Energy					
Battery Type		Lithium Iron Phosphate		Lithium Iro	n Phosphate
Battery Voltage/Rated Capacity		48 V / 40 Ah		24 V /	′ 210 Ah
BMS Communication Protocol		CAN		C	AN
Charging Type		Contact Charging		Contact	Charging
Charging Speed		< 2h		<	: 2h
Perception					
Navigation Sensor		Bracket Included		Bracket	Included
Object Detection Lidar		Optional		Opt	ional
Encoders		Optional		Opt	ional
Fork Tip Sensor		Bracket Included		Bracket	Included
Pallet Detection Camera		Space Included		Space	Included
Bumper Pressure Sensor		Included		Incl	uded
Others					
Communication		Dual-band Wi-Fi		Dual-ba	and Wi-Fi
HMI		7 Inch HMI Included		7 Inch HN	11 Included
Speaker/Light Beam/E-Stop Buttons/Status Light		Included		Incl	uded

Note: Customization available on request.

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# Motion System





#### Comprehensive Portfolio

Covers wheel modules, actuators, transmission units, and lifting mechanisms, providing a one-stop solution for robotic mobility



#### Modularity & Scalability

Flexible architecture allows easy customization and adaptation to different payloads, sizes, and application scenarios



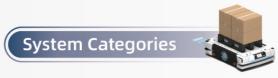
#### Versatile Motion Capabilities

Supports differential drive, steering wheel, Mecanum, and omnidirectional configurations to meet diverse mobility needs



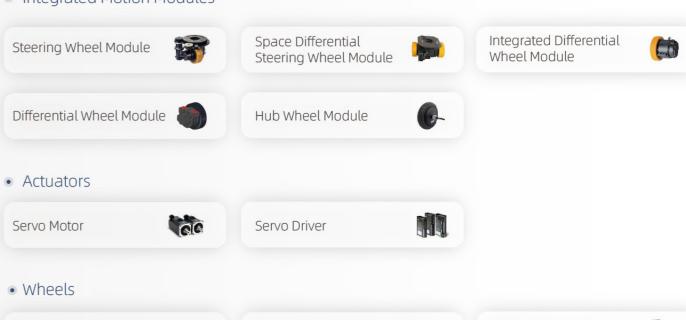
#### Future-Ready Platform

Provides the foundation for next-generation AGVs, AMRs, and robotics, enabling innovation in logistics, manufacturing, and beyond



### **MOTION:**

Integrated Motion Modules



#### Platforms

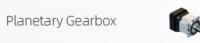
Traction Wheel

Lifting and Rotating Mechanism



Transmission

Universal Wheel



### Application Examples



Single steering wheel chassis model



Mecanum wheels integrated cobots



Mecanum Wheel

Motor mounted on differential wheel

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### **AB-SW-Customized Model**





The AB-SW-Customized Model is an integrated motion solution designed for mobile robots such as AGVs and AMRs in industrial environments. It combines a drive motor, steering motor, precision gearbox, and encoder feedback system into a compact and modular assembly, optimized for high performance and flexible mobility.

This series supports a wide range of configurations, offering various wheel diameters, gear ratios, motor voltages, and encoder types to meet different application needs.

Туре	Model		Specification			Drive Motor		Steering Motor			
		Voltage	Payload	Wheel Diameter	Height	Weight	Power	Nominal Torque	Power	Nominal Torque	Turning
		(V)	(kg)	(mm)	(mm)	(kg)	(kW)	(N·m)	(kW)	(N·m)	Turning
	AB-SW-D150-P0.75-C500-V	24/48	500	150	413.5	25	0.75	38	0.2	68	±180°
120x	AB-SW-D230-P3.0-C1500-V	48	1500	230	508.5	80	3	177.65/218.03	0.4	334.56	±130°
	AB-SW-D300-P4.0/5.0-C2000-V	48	2000	300	768	95	4.0/5.0	182.33/364.65	0.75	533.27	±180°
	AB-SW-D105-P0.4-C300	48	300	105	155	17.5	0.4	34.8	0.1	77.11	±120°
	AB-SW-D125-P0.4-C350	48	350	125	175	17.5	0.4	26.11/34.82	0.1	77.11	±120°
	AB-SW-D150-P0.75-C600	48	600	150	173	21	0.75	40.63/60.01	0.1	67.32	±120°
	AB-SW-D150-P1.0-C600	48	600	150	173	21	1	54.40/87.04	0.1	67.32	±120°
	AB-SW-D160-P0.4-C350	24/48	350	160	194	21	0.4	21.59/34.54	0.2	34.27	±141°
	AB-SW-D160-P0.75-C800	24/48	800	160	203	21	0.75	65.01	0.1	72.22	±120°
	AB-SW-D160-P1.0-C1000	48	1000	160	203	21	1	54.40/87.04	0.1	72.22	±120°
	AB-SW-D150-P0.4-C600	48	600	150	173	21	0.4	21.59/34.54	0.1	29.92	±120°
	AB-SW-D180-P1.5-C1000	48	1000	180	245	25	1.5	97.38	0.2	72.22	±120°
	AB-SW-D200-P0.75-C1000	48	1000	200	265	43	0.75	102	0.2	144.43	±120°
	AB-SW-D200-P1.0-C1500	48	1500	200	265	43	1	136	0.4	239.9	±120°
	AB-SW-D200-P1.0-C1000	48	1000	200	265	43	1	97.30/129.74	0.2	288.86	±120°
	AB-SW-D200-P1.5-C1500	48	1500	200	265	43	1.5	129.74	0.4	239.9	±120°
	AB-SW-D200-P3.0-C1500	48	1500	200	265	43	3	193.8	0.4	239.9	±120°
	AB-SW-D250-P1.0-C1000	24/48	1000	250	300	43	1	65.28-129.74	0.4/0.2	119.95 - 288.86	±120°
	AB-SW-D250-P1.5-C1500	48	1500	250	300	43	1.5	97.31-129.74	0.4	239.9	±120°
	AB-SW-D250-P3.0-C1500	48	1500	250	300	48	3	193.80-367.20	0.4/0.2	119.95 - 288.86	±120°
	AB-SW-D280-P3.0-C3000	48	3000	280	358	80	3	88.83-177.65	0.75	497.72	±120°
	AB-SW-D300-P3.0-C3000	48	3000	300	386	80	3	323	0.75	497.72	±120°
	AB-SW-D300-P4.0/5.0-C3500	48	3500	300	385	95	4.0/5.0	994.5	1	666.4	±120°
	AB-SW-D410-P4.3-C4500	48	4500	410	525	200	4.3	1606.50/2295.00	1	2040	±110°
	AB-SW-D410-P5.7-C4500	48	4500	410	525	200	5.7	1606.50/2295.00	1	2040	±110°
	AB-SW-D500-P5.5-C6000	48	6000	500	616	350	5.5	2142	1.5/3	1508.27 - 17212.50	±120°
	AB-SW-D500-P7.5-C6000/10000	48	6000/10000	500	616	350	7.5	4896	1.5/3	1508.27- 17212.50	±120°
	AB-SW-D550-P7.5-C15000	96	15000	550	690	450	7.5	4896	3	4562.38	±120°
	AB-SW-D550-P20-C15000	96	15000	550	690	450	20	3332	3	4562.38	±120°



### **AB-DDS-Customized Model**



#### **Key Features**

**▶□1** • Simplified Differential Architecture

Achieves forward, reverse, and turning motion using only two independently driven wheels—ideal for compact chassis

Integrated Motion Unit

Combines servo motors, high-torque gearboxes, encoders, and optional support wheels into one modular system

High Payload Capability

Supports payloads ranging from 400 kg to 10,000 kg, with torque-optimized motor and reducer combinations

Precision Feedback Control

Built-in encoders enable closed-loop speed and direction control; supports both incremental and absolute types

Optimized for Indoor AGVs

Designed for smooth operation on flat surfaces, offering reliable performance in logistics, warehousing, and manufacturing settings

Flexible Configuration Options Available with multiple wheel diameters (85-400 mm), motor voltages, encoder protocols, and communication interfaces such as CANopen or RS485

The AB-DDS-Customized Model is a compact and cost-effective motion platform designed for AGVs and AMRs operating in indoor industrial environments. Using a differential drive mechanism, it enables precise linear and rotational movement by independently controlling the speed and direction of two drive wheels—eliminating the need for complex steering components.

#### Engineered for Modern AGV & AMR Platforms:



Rated Voltage: 24/48V

Encoder:

Supports Incremental Absolute/Safety

**Communication Method:** 

CAN(EtherCAT/RS485 Optional)

Applicable Scenarios:

Forklift Stacker, Pallet Truck, Lifting AMR/AGV, Platform AMR/AGV, Heavy Duty AGV, Elevated Work Platform, etc.

#### **Parameter List**

Model		Sp	ecification		Drive Motor	
	Voltage	Payload	Wheel Diameter	Height	Power	Nominal Torque
AB-DDS-D75-P0.4-C400	48 V	400 kg	75 mm	95 mm	0.4 kW	6.477
AB-DDS-D85-P0.2-C450	48 V	450 kg	85 mm	107.2 mm	0.2 kW	4.08
AB-DDS-D170-P0.75-C1000	48 V	1000 kg	170 mm	247 mm	0.75 kW	48.552
AB-DDS-D205-P0.75-C1000	48 V	1000 kg	205 mm	264.5 mm	0.75 kW	64.736
AB-DDS-D210-P1.5-C2000	48 V	2000 kg	210 mm	260 mm	1.5 kW	97.308
AB-DDS-D240-P1.5-C2000	48 V	2000 kg	240 mm	265 mm	1.5 kW	97.92
AB-DDS-D300-P3.0-C3000	48 V	3000 kg	300 mm	382.5 mm	3.0 kW	323
AB-DDS-D300-P2.0-C6000	48 V	6000 kg	300 mm	354.5 mm	2.0 kW	299.2
AB-DDS-D400-P3.0-C10000	48 V	10000 kg	400 mm	482 mm	3.0 kW	972.4
AB-DDS-D500-P4.2-C16000	48 V	16000 kg	500 mm	559 mm	4.2 kW	1836



### **AB-iDW-Customized Model**



The IWMC Integrated Servo Wheel is an all-in-one integrated servo wheel solution engineered for mobile robots, AGVs, and AMRs requiring compact design and high dynamic performance.

<65 dB Natural Cooling with Vehicle-Assisted Heat Dissipation

0 - 40 °C

-20 - 60 °C

Below 90% RH

IP54

Rated operating altitude is below 1000 m. For operating altitudes above 1000 m, the power rating must be derated by 1.5% for every 100 m increase. The maximum operating altitude is 2000 m

86 kpa - 106 kpa









**Cooling Method** 

Operating

**Environment** 

**Operating Temperature** 

Storage Temperature

**Atmospheric Pressure** 

(Non-condensing)

Humidity

**IP Ratings** 

Altitude



1odel		AB-iDW-D150-V3.9-C100-■	AB-iDW-D165-V1.9-C300-■	AB-iDW-D180-V2.14-C500-■	AB-iDW-D180-V1.57-C700-■	AB-iDW-D180-V1.57-C750-■	AB-iDW-D180-V1.18-C∙					
Server Cumply	Main Power Supply			24VDC	- 60VDC							
ower Supply	Logic Power Supply	/	24VDC									
Rated Linear Speed	(m/s)	3.9	1.9	2.14	1.57	1.57	1.18					
ated Torque Tn (N	m)	3.6	21	40	54	60	80					
Peak Torque Tn (Nm)		10.9	60	99	150	150	200					
Tire Diameter (mm)		150	165	180	180	180	180					
Tire Width (mm)		40	39.5	50	50	50	50					
Tire Material Polyurethane (Optional)												
Tire Hardness Rating 73 A			85 A	90 A		93 A ± 2						
ynamic Braking			External braking re	sistor required (depending on ope	rating conditions, mainly used in	rapid start-stop scenarios)						
ynamic Braking V	oltage Absorption Point	None			DC63 V ± 2 V							
Overvoltage Alarm	Voltage			DC68	V ± 2 V							
Indervoltage Aları	n Voltage		$DC18V \pm 2V$									
nput Specification			2 digital inputs / Common COMI terminal / High level: 12.5-30 VDC / Low level: 0-5 VDC / Max. frequency: 1 kHz / Input impedance: 5 kΩ									
Output Specificatio	ns			1 digital output, common COMO to	erminal / Max. output current: 100	) mA						
Brake				Built-in Brake a	nd Control Circuit							
orced Brake Relea	se Interface		One force	d brake release interface, to be us		no power input						
S485 Debug Port			Maximum supported baud rate: 115.2 Kbps									
AN BUS			Maximum	baud rate: 1 Mbps; supports com	munication with controllers via CA	Nopen protocol.						
rive Current	Max. Continuous Output	7 A	16 A	26 A	25 A	27 A	27 A					
inve current	Peak Current (PEAK)	26 Ap	64 AP	100 Ap(<2s)	100 Ap(<2s)	100 Ap(<2s)	100 Ap(<2s)					
	Rated Speed nN (rpm)	3000	2000	2500	2500	2500	2500					
/lotor	Rated Torque Tn (Nm)	0.64	2.4	4	4	4.4	4.4					
	Brake Holding Torque T	2	4	4	4	4	4					

Note: ■ = B: With Brake 123 24



#### **AB-DW-Customized Model**



#### **Key Features**



☐ ■ Integrated Drive Wheel

Motor, reducer and wheel combined in one compact unit



• Independent Wheel Control

Enables differential steering for agile, precise navigation



High Load Capacity

Supports payloads up to 1500 kg (two-wheel system)



Compact Modular Design

Simplifies chassis integration and saves installation space



✓ Quiet and Energy-Efficient

Optimized for low-noise, smooth operation with minimal energy consumption.

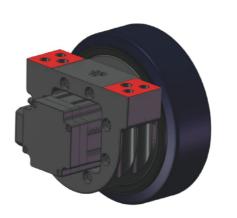


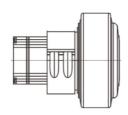
Multiple Options

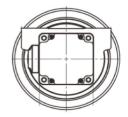
Various diameters, power ratings and speed configurations to meet different application needs

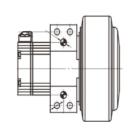
The AB-DW-Customized Model is a high-performance drive wheel designed for mobile robotics, AGVs and other autonomous platforms. Each wheel integrates a motor, planetary reducer and wheel assembly into a compact unit, enabling precise and smooth maneuvering through independent control of left and right wheels.

The DW Series provides multiple sizes and load capacities to suit a wide range of applications, from light-duty service robots to heavy industrial vehicles.









	S	pecification			Driver	Motor		Reducer
Typical Madel	Payload(2 sets)	Wheel Diameter	Speed	Voltage	Motor Power	Motor Speed	Torque	Ratio
Typical Model	(kg)	(mm)	(m/s)	(V)	(W)	(RPM)	(N·m)	Kaliu
AB-DW-D120-P0.4-C800	800	120	1.15±0.01	48	400	3000	1.27	16
AB-DW-D140-P0.4-C700	700	140	1.35±0.01	48	400	3000	1.27	16
AB-DW-D150-P0.4-C650	650	150	1.45±0.01	48	400	3000	1.27	16
AB-DW-D150-P0.75-C1200	1200	150	1.45±0.01	48	750	3000	2.39	16
AB-DW-D160-P0.4-C600	600	160	1.55±0.01	48	400	3000	1.27	16
AB-DW-D160-P0.75-C1100	1100	160	1.55±0.01	48	750	3000	2.39	16
AB-DW-D180-P0.4-C500	500	180	1.75±0.01	48	400	3000	1.27	16
AB-DW-D180-P0.75-C1000	1000	180	1.75±0.01	48	750	3000	2.39	16
AB-DW-D200-P0.4-C450	450	200	1.95±0.01	48	400	3000	1.27	16
AB-DW-D200-P0.75-C900	900	200	1.95±0.01	48	750	3000	2.39	16
AB-DW-D220-P1.5-C1500	1500	220	2.15±0.01	48	1500	3000	4.77	16
AB-DW-D250-P1.5-C1500	1500	250	2.45±0.01	48	1500	3000	4.77	16

Note1: Reducer Ratio: 16/20/25/28/35/40/50/70, customied

Note2: Brake(optional)—With/Without

Note3: Encoder(optional)—Magnetic Encoder; Multi-turn Magnetic Absolute Encoder; 2500 P/R Optical Encoder; 2500 P/R Incremental Magnetic Encoder

Note4: Max.Payload—4000kg(Wheel Diameter—220mm, Reducer Ratio—70, Max.speed—0.5±0.01m/s)

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#### **AB-HW-Customized Model**



#### **Key Features**



Compact, Space-Saving Design

Available in 107-388 mm wheel sizes—ideal for installation in confined mobile systems



Payload Capacity

Supports loads ranging from 60 kg up to 150 kg, depending on wheel size and power rating



Torque Output

Delivers torque from 2 Nm to 20 Nm across the product line



High Integration & Responsiveness

Direct-drive architecture integrates electrical and mechanical parts, offering fast torque response and agile motion—perfect for dynamic robot behavior



Cost-Effective & Easy to deploy

Simplified mechanical structure reduces both manufacturing and maintenance costs. The plug-and-play design accelerates assembly and deployment



Ideal for Service Robots

Well-suited to delivery, cleaning, inspection, and sorting robots, especially in environments such as restaurants, hospitals, offices, and factory floors

The hubwheel motor is a highly integrated drive solution that combines the motor, gearbox, and sensor modules directly within the wheel. It enables direct drive for Service Robot systems, offering compact design, fast response, easy installation, and low maintenance. Widely used in AGVs, AMRs (Autonomous Mobile Robots), and intelligent logistics platforms, hub motors significantly enhance system efficiency and reliability.

#### Integrated hub motor for Service Robot precise drive







Model	Wheel Diameter (mm)	Payload (kg)	Power (W)	Voltage (V)	Torque (N·m)	Encoder	Rated Speed (RPM)	Weight (kg)
AB-HW-D107-P0.1-C50	107	50	100	24	2	1024/2500/4096 Lines, Absolute Value	450	1.5
AB-HW-D128-P0.2-C150	128	150	200	24	5	1024 Lines	300	3
AB-HW-D130-P0.1-C30	130	30	100	24	3	1024/2500/4096 Lines, Absolute Value	270	2
AB-HW-D139-P0.15-C30	139	30	150	24	3	1024 Lines	270	2
AB-HW-D170-P0.25-C75	170	75	250	24	6.5	1024/2500/4096 Lines, Absolute Value	200	3
AB-HW-D200-P0.25-C50	200	50	250	24	4	1024/2500/4096 Lines, Absolute Value	500	3.5
AB-HW-D200-P0.4-C150	200	150	400	48	20	1024/2500/4096 Lines, Absolute Value	150	8.5
AB-HW-D239-P0.4-C150	239	150	400	48	20	1024/2500/4097 Lines, Absolute Value	150	9
AB-HW-D266-P0.4-C150	266	150	400	48	20	1024/2500/4098 Lines, Absolute Value	150	9.5
AB-HW-D337-P0.4-C150	337	150	400	48	17	1024/2500/4099 Lines, Absolute Value	150	9.5
AB-HW-D358-P0.4-C150	358	150	400	48	17	1024/2500/4100 Lines, Absolute Value	150	9.6
AB-HW-D388-P0.4-C150	388	150	400	48	17	1024/2500/4101 Lines, Absolute Value	150	9.7

### **Actuators**

1 Servo Motor







### **Servo Motor**



The Servo Motor is a compact and intelligent DC servo motor solution designed for high-performance mobile and embedded applications. Featuring integrated driver, motor, encoder, and optional brake, this all-in-one unit simplifies system design while providing precise torque, speed, and position control.

Model	Flange Size (mm)	Rated Power Pn(W)	Rated Torque Tn(Nm)	Rated Current In(A)	Rated Speed nN(rpm)
SMC40S-0005-30■□K	4040	50	0.16	1.5	
SMC40S-0010-30 ■ □ K	40x40	100	0.32	3.2	
SMC60S-0020-30 ■ □ K		200	0.64	5.7	
SMC60S-0040-30 ■ □ K		400	1.27	10.6	
SMC60S-0060-30 ■ □ K	60x60	600	1.91	16.5	
SMK60S-0020-30 ■ □ K		200	0.64	5.7	
SMK60S-0040-30 ■ □ K		400	1.27	10.6	
SMC80S-0075-30 ■ □ K		750	2.39	19.9	
SMC80S-0100-30 ■ □ K		1000	3.18	26.4	
SMC80S-0120-30 ■ □ K	80x80	1200	3.82	34	3000
SMC80S-0150-30 ■ □ K	OUXOU	1500	4.77	37.4	
SMK80S-0075-30 ■ □ K		750	2.39	19.2	
SMK80S-0100-30 ■ □ K		1000	3.81	25.8	
SMH110D-0120-30■□K	110x110	x110	4	32	
SMC130D-0120-30 ■ □ K		1200	3.8	31.6	
SMC130D-0150-30 ■ □ K		1500	5	37.5	
SMC130D-0150-30 ■ □ K	130x130	1500	5	42.4	
SMC130D-0250-30 ■ □ K	130X130	2500	7.96	61	
SMC130D-0300-30 ■ □ K		3000	9.55	72	
SMC130D-0300-20 ■ □ K		3000	14.3	77.7	2000
SMK180G-0300-20 ■ □ K		3000	14.33	37.5	
SMK180G-0400-20 ■ □ K	180x180	4000	19.1	50	2000
SMK180G-0500-20 ■ □ K-		5000	23.88	62.6	

Note 1:

■= M: Magnetic Encoder ■= M: Magnetic Encoder ■= Q: Multi-turn Magnetic Absolute Encoder

■= W: 2500 P/R Incremental Magnetic Encoder

■= A: 2500 P/R Optical Encoder

Note 2:

 $\square$  = A: Without Brake = B: With Brake

#### **DC Servo Drive**



The DC Servo Drive delivers top-tier intelligent servo control optimized for AGVs, AMRs, industrial automation, and robotic applications. This versatile drive accommodates multiple operational modes such as position, velocity, and torque control, seamlessly interfacing with both brushless DC servo motors.

Incorporating sophisticated vector control techniques and rapid response capabilities, our product guarantees stable, smooth motion and enhances system robustness. It offers extensive communication options and configurable settings to adapt to a wide variety of application demands.

#### **Key Features**



#### Integrated Servo Design

Combines motor, driver, encoder, and brake in a single enclosure, minimizing wiring and footprint.



#### High Responsiveness

Delivers smooth torque output and precise motion through closed-loop control with low latency.

#### Multiple Power Ratings

Available in a wide range of voltage and power configurations (e.g. 24V/48V, 50W-3000W), supporting dynamic load conditions.



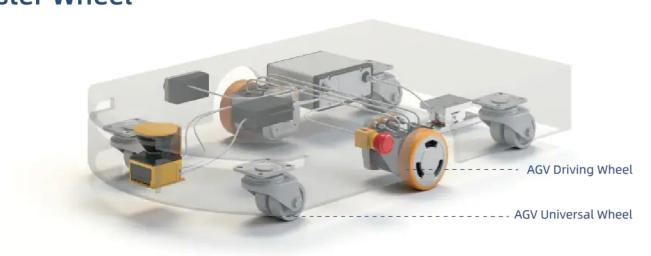
#### Optional Electromagnetic Brake

Enables safe holding and emergency stop in power-loss or fault conditions.

Model	Power(W)	Max. Continuous Output Current (RMS) (A)	Peak Current (AP)	Brake Power Supply	24V Logic Power Supply
FD114S-C□-000	50 - 100	5	8	•	•
FD124S-C□-000 FD124S-C□-000	200 - 400	15 (12A without additional cooling)	48	0	•
FD134S-C□-000 FD134S-C□-000	750	25 (20A without additional cooling)	80	0	•
FD144S-C□-000 FD144S-C□-000	1.2 - 1.5 k	40 (30A without additional cooling)	120	0	•
FD164S-C□-000	2.5 - 3 k	80 (60Awithout additional cooling)	240	•	•
Note 1: □ = C:CANopen	□ = L:RS485/Pu	lse □ = E:EtherCAT			

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### **Caster Wheel**



#### **Model Overview**





























The AGV Driving Wheel is a high-load-capacity drive wheel module designed for industrial AGVs and AMRs requiring reliable traction, smooth motion, and long service life. Built with a reinforced metal core and wear-resistant polyurethane tread, it ensures excellent grip and stability under continuous operation.

#### **Key Features**

#### High Load Capacity

Supports up to 500kg per wheel, suitable for medium to heavy-duty AGV platforms. Durable PU Tread Provides excellent wear resistance, low rolling resistance, and quiet operation on industrial floors

#### Optimized for Servo Integration

Compatible with flange-mounted servo motors and gearboxes for precise motion control

#### Robust Construction

Industrial-grade metal hub and sealed bearings ensure mechanical strength and minimal maintenance

#### Flexible Customization

Available in multiple diameters, widths, and mounting configurations to meet various design needs

#### Hub Fitting

Model	AB-TW-D130-C200-EP	AB-TW-D150-C250-EP	AB-TW-D150-C250-HP	AB-TW-D150-C280-FS	AB-TW-D200-C300-EP	AB-TW-D180-C400-EP	AB-TW-D200-C500-EP	AB-TW-D200-C400-FS
Material	Polyurethane 73 shore A	Polyurethane 73 shore A	Polyurethane 80 shore A	Polyurethane 93 shore A	Polyurethane 73 shore A	Polyurethane 83 Shore A	Polyurethane 93 Shore A	Polyurethane 83 Shore A
Grain	Embossed Pattern	Embossed Pattern	Herringbone Pattern	Flat Surface	Embossed Pattern	Embossed Pattern	Embossed Pattern	Flat Surface
Core Material, Color		Cast Iron /	Black Paint		Cast Iron / Black Paint	Aluminum / Orignial Color	Aluminum/ Black Paint	Aluminum / Black Paint
Wheel Diameter (mm)	130		150		200	180	200	200
Tread Width (mm)	40		40		40	50	50	42
No. of Fixing Holes	6-M5		6- Ф6.5		6- Ф6.5	6×6.6 2×M6	4×7 2×M8	6×M8
Central Hole (mm)	35		50		50	40	115	115
PCD(mm)	45		70		70	65	133	133
Max. Load Capacity (kg)	200	250	250	280	300	400	500	400

#### Keyway

Model	AB-TWK-D130-C250-EP	AB-TWK-D200-C300-EP	AB-TWK-D125-C300-EP	AB-TWK-D150-C400-EP	AB-TWK-D200-C500-EP				
Material	Polyurethane 73A	Polyurethane 93A	Polyurethane 93A	Polyurethane 73A	Polyurethane 93A				
Grain		Embossed Pattern							
Core Material, Color		Cast Iron / Black Paint							
Wheel Diameter (mm)	130	200	125	150	200				
Tread Width (mm)	51	45	50	50	50				
Axle Bore (mm)	20	16	25	25	25				
Hub Groove Length (mm)	6	5	8	8	8				
Hub Groove Height (mm)	23	18	28	28	28				
Max. Load Capacity (kg)	250	300	300	400	500				

### Wheel

### Universal Wheel(UW Series)



The AGV Universal Wheel is a precision universal caster wheel module used as an auxiliary support wheel on AGVs and AMRs. Designed for 360° rotation and omnidirectional mobility, it ensures smooth turning, structural balance, and low-friction movement during autonomous navigation.

With a dual-wheel configuration and high-grade polyurethane surface, the UCW module reduces vibration and enhances maneuverability in space-constrained environments such as warehouses, factories, and cleanrooms

#### **Key Features**

- Omnidirectional Swivel Motion
- Dual-Wheel Structure

Provides better weight distribution and rolling stability under dynamic loads.

• Quiet, Floor-Friendly Operation

Polyurethane wheels reduce noise and protect flooring surfaces during long-term use.

Compact & Low Profile

Low center of gravity improves AGV stability, especially when turning or braking.

Industrial Durability

Steel frame and sealed bearings ensure long operational life in continuous-duty environments.

#### Universal Wheel

Model	AB-UW-D25-C30	AB-UW-D57-C100	AB-UW-D50-C150	AB-UW-D55-C200	AB-UW-D65-C200	AB-UW-D76S-C150	AB-UW-D76S-C200	
Tread Material	PU 55D		PU	93A		PU 73A	PU 93A	
Hub Material	PU 73A		Aluminum					
Wheel Dia (mm)	25	57	50	55	65	76	76	
Wheel Width (mm)	15	14×2	20×2	20×2	24×2	24×2	24×2	
Total Height (mm)	37	80	82	79	87	107	107	
Radius (mm)	16	22	20	20	20	20	20	
Top Plate (mm)	30×38	67×49	111×80	84×84	111×80	104×82	104×82	
Bolt Hole Centers (mm)	29×21	52×35	87/78×60	64/59×64/59	87/78×60	87/78×60	87/78×60	
Attaching Bolt Size (mm)	4	8	9	9	9	9	9	
Max. Load Capacity (kg)	30	100	150	200	200	150	200	

Model	AB-UW-D76-C200	AB-UW-D76-C150	AB-UW-D76-C300	AB-UW-D80-C500	AB-UW-D100-C600	AB-UW-D150-C1000	AB-UW-D200-C1500	
Tread Material	PU 73A	PU 73A	PU	J 93A	PU 55D			
Hub Material	Aluminum			Steel 45#	Iron			
Wheel Dia (mm)	76	76	76	80	100	150	200	
Wheel Width (mm)	24×2	24×2	30×2	35×2	35×2	40×2	40×2	
Total Height (mm)	107	107	110	110	133	191	268	
Radius (mm)	20	20	22	21	21	45	57	
Top Plate (mm)	110×85	110×85	116×110	116×100	116×100	159×115	185×135	
Bolt Hole Centers (mm)	86×60	86×60	92/76×76/67	78×78	78×78	133/125×86/62	155/132×105/85	
Attaching Bolt Size (mm)	9	9	11	9	9	14	14	
Max. Load Capacity (kg)	200	150	300	500	600	1000	1500	

### Wheel



**Mecanum Wheel** 

The AB-MW series Mecanum wheels are designed to provide omnidirectional mobility, allowing AGVs, robotics platforms, and industrial transport systems to move smoothly in any direction—forward, backward, sideways, or diagonally—without the need for traditional steering mechanisms.

Material **Casting Polyurethane** 

Wheel Diameter **100 - 836 mm** 

Payload Capacity
200kg-40000kg







Model	Wheel Diameter (mm)	Payload(4 wheel) (kg/set)	Weight (kg/pcs)	Torque(N·m)	Max.Speed(m/s)	
AB-MW-D100-C250	100	250	0.7			
AB-MW-D120-C300	127	300	2			
AB-MW-D152-C500	152	500	2.6			
AM-MW-D176-C600	176	600	3			
AB-MW-D203-C800	203	800	4.5			
AB-MW-D254-C1500	254	1500	13.5			
AB-MW-D280-C2000	280	2000	15	Note:		
AB-MW-D305-C3000	305	3000	17.5	1. Reference va	lues: Motor speed —	
AB-MW-D330-C3500	330	3500	25	—3000RPM,	Reduction ratio——	
AB-MW-D355-C4500	355	4500	32	1:50, Max. Sp	peed 0.5m/s - 1m/s.	
AB-MW-D375-C5000	375	5000	40	2. Customized a	according to the	
AB-MW-D406-C6000	406	6000	45	motor speed	and the reduction	
AB-MW-D457-C8000	457	8000	60	ratio of the re	educer.	
AB-MW-D475-C9000	475	9000	75			
AB-MW-D508-C10000	508	10000	80			
AB-MW-D558-C15000	558	15000	110			
AB-MW-D609-C20000	609	20000	143			
AB-MW-D660-C30000	660	30000	196			
AB-MW-D836-C40000	836	40000	300			

MOTION

### Lifting and Rotating Mechanism

### **AB-LRP-Customized Model**



The Lift Module is a robust, precision-engineered scissor-type lifting solution tailored for AGV and AMR applications. It enhances flexibility and ergonomics by enabling height-adjustable load handling—whether for loading, unloading, interfacing with machinery, or adapting to varying floor levels. Its compact structure and dependable performance make it ideal for modern automation environments.

#### **Key Features:**

- Disc lift mechanism for vertical adjustment of payloads—precise and smooth motion control
- Flexible load interfacing —————— supports loading directly onto the lift, via conveyors, rollers, or fixtures
- High payload capacity: supports up to 2,000 kg in heavy-duty configurations (customizable to project requirements)

	Lift Parameters			Lift Motor Parameters				Rotation	Others	
Model	Route (mm)	Reducer Ratio	Up/Down Speed (mm/s)	Load (kg)	Power (W)	Voltage (V)	Torque (N·m)	Ratio	Rotate 90° (s/90°)	Weight (kg)
AB-LRP-P400-L60-C500	60	40	6.25	500	400	48	1.27	241.6	1.21	30
AB-LRP-P600-L50-C1000	50	40	7.5	1000	600	48	1.91	355.6	1.78	58
AB-LRP-P750-L50-C1500	50	49.5	10	1500	750	48	2.39	202.5	1.01	88.8
AB-LRP-P1200-L50-C2000	50	49.5	10	2000	1200	48	4	202.5	1.01	88.8



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#### MOTION

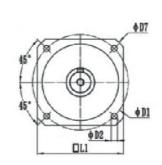
### Planetary Gearbox

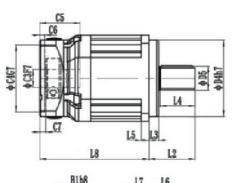


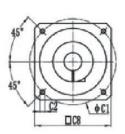
### **AB-PGT-Customized Model**



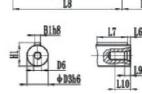
The AB-PGT series of high-precision planetary gearboxes is designed for servo and stepper motor applications, offering compact size, high efficiency, and long-term reliable operation. Engineered for demanding industrial environments, these gearboxes provide excellent torque handling, minimal maintenance, and superior performance under varying conditions.

















Model	Stage	Ratio	Nominal Torque	Nominal Input Speed	Max. Radial Load	Max. Axial Load	Precise Backlash	Noise
AD DCT 542.11 □ ■	1	4 10	(N·m)	(rpm)	(N)	(N)	(arcmin)	(dB)
AB-PGT-F42-L1-□-■	1	4 - 10	14 - 23	3000	770	330	3	58
AB-PGT-F42-L2-□-■	2	12 - 90	14 - 23	3000	770	330	5	58
AB-PGT-F60-L1-□-■	1	3 - 10	42 - 65	3000	1500	700	3	60
AB-PGT-F60-L2-□-■	2	12 - 90	42 - 65	3000	1500	700	5	60
AB-PGT-F90-L1-□-■	1	3 - 10	105 - 165	3000	3200	1600	3	60
AB-PGT-F90-L2-□-■	2	12 - 90	105 - 165	3000	3200	1600	5	60
AB-PGT-F115-L1-□-■	1	3 - 10	220 - 345	3000	6700	3300	3	63
AB-PGT-F115-L2-□-■	2	12 - 90	255 - 345	3000	6700	3300	5	63
AB-PGT-F142-L1-□-■	1	3 - 10	450 - 700	3000	9300	4500	3	65
AB-PGT-F142-L2-□-■	2	12 - 90	455 - 700	3000	9300	4500	5	65
AB-PGT-F180-L1-□-■	1	3 - 10	910 - 1431	2000	14000	7000	5	67
AB-PGT-F180-L2-□-■	2	12 - 90	910 - 1568	2000	14000	7000	7	67
AB-PGT-F220-L1-□-■	1	3 - 10	1500 - 2567	2000	16000	8000	5	70
AB-PGT-F220-L2-□-■	2	12 - 90	1500 - 2567	2000	16000	8000	7	70

Note:

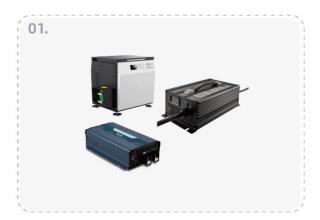
1. Output Type-□: S1-Shaft; S2-Shaft With Key; S3-Splinde Shaft; K1-Hollow Shaft; K2-Hollow With Key; K3-SWpine hollow; OP3-Case Mounting; OP4-Foot Mounting; 2. Structure -■: R-Right Angle; L: Line

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# **ATOMBOTIX Energy** General Introduction

Our Energy System is a comprehensive, modular power solution designed specifically for autonomous mobile platforms such as AGVs and AMRs. Engineered for high efficiency, safety, and long-term reliability, the system integrates charging technology and energy storage into a unified architecture that ensures continuous uptime in demanding industrial environments.

#### Our Energy System includes the following core products:



Contact Charging Series high-efficiency, safe AGV/AMR docking power solution



Lithium-ion Battery Series efficient, reliable contactless AGV/AMR charging solution



Wireless Charging Series compact, wide-range, protected industrial power supply



DC-DC Series safe, durable, expandable AGV/AMR energy storage

### Contact Charging series

Our Contact Charging Module is a high-efficiency, industrial-grade charging solution designed for AGV and AMR platforms. Using direct-contact power transmission, it delivers fast, safe, and reliable energy transfer during autonomous docking, with support for high current and flexible installation layouts.

#### **Key Features:**

- ▶ High-power fast charging: 1.2-4.8 kW power, up to 200 A current, suitable for large-capacity batteries
- Multi-voltage compatibility: Supports 24 V and 48 V systems, compatible with lithium and lead-acid batteries
- ▶ Smart communication: CAN, Modbus, and Wi-Fi protocols for real-time control and monitoring
- Safety protection: Multiple protections including OVP, OCP, reverse polarity, backflow, and OTP
- Strong adaptability: Brush plate or telescopic contact design, wide height range, fits multiple vehicle types

#### **Application Scenarios:**







# Contact Charging

#### • NPB-1200

Wide Range Adjustable Output

90-264Vac Input 50-100% adjustable current

Compatibility Mode

CAN Bus Support 2-stage/3-stage charging - Configurable via DIP switch

Model	AB-CM-1200-24	AB-CM-1200-48					
Output Voltage	27.6 V	55.2 V					
Output Current	36 A	18 A					
Max. Power	1209.6 W	1209.6 W					
Battery Capacity	120 -420 Ah	60-210 Ah					
Efficiency	93%	94%					
Input Voltage	90 - 264 V	AC					
Safety Specification	CB IEC62368-1,IEC60335-1/2-29, Dekr	a BS EN/EN62368-1,BS					
Protection	OVP / OTP / SCP / Reve	erse Polarity					
CANBUS Interface	CANBus 2.0	CANBus 2.0B					
Operating Temperature	-30°C to +	70°C					

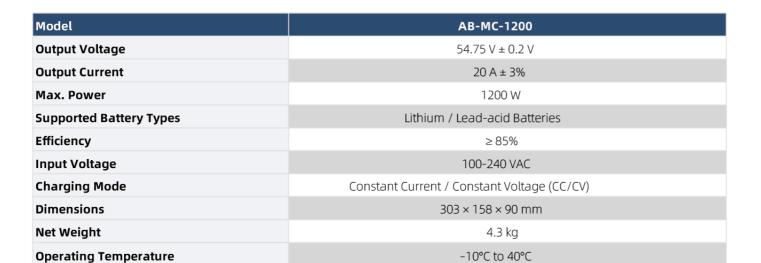
### Manual Charger-1200W

Rated Input Voltage Rated Output Current

100-240VAC ≤58.8V20A

Rated Output Power Communication Method

1200W CAN



### • CC-Compact Charger

Wide Range High Efficiency 220VAC±15% ≥ 92

Capacity Communication

2.4kW battery charger CAN



Model	AB-CC-2400-24	AB-CC-2400-48			
Output Voltage	16-32 VDC	30-65 VDC			
Output Current	100 A 50 A				
Rated Power	2.4	kW			
Efficiency	≥92	2%			
Input Voltage	220 VAC ±15%				
Comm. Protocol	CAN / Modbus / Wi-Fi				
Charging Mode	AGV contact /	Telescopic			
Protection	OVP / OCP / Reverse	e Polarity / Backflow			
Dimensions	540 × 580 >	< 390 mm			
Weight	35 kg				
Operating Temp.	-20°C to +65°C				
AGV Brush Plate Center Ground Clearance	90 mm - 400 mm				

### SCC-Split-type Compact Charger

Wide Range High Efficiency 220VAC±15% ≥ 92

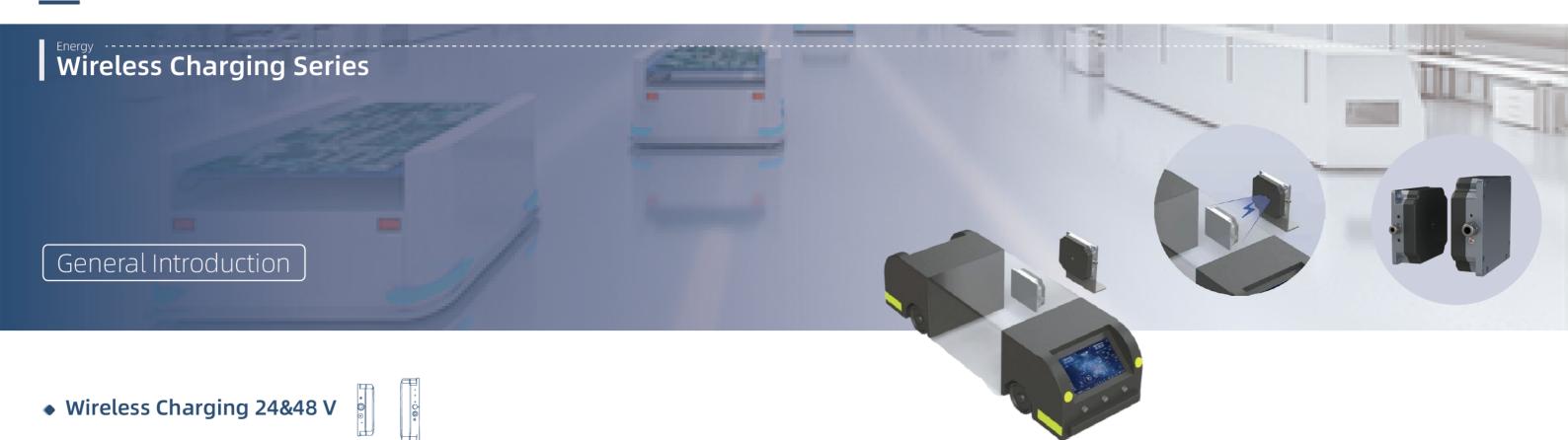
Capacity

4.8 kW battery charger CAN



Model	AB-SCC-2400-24	AB-SCC-2400-48	AB-SCC-4800-24	AB-SCC-4800-48	
Output Voltage	16-32 VDC	32-64 VDC	16-32 VDC	32-60 VDC	
Output Current	0-100 A	0-50 A	0-200 A 0-100 A		
Rated Power	2.4 kW	2.4 kW	4.	8 kW	
Efficiency	≥92%	≥92%	≥92%		
Input Voltage	220VAC ±15% 220VAC ±15% 220VAC ±15%			AC ±15%	
Comm. Protocol	CAN, Modbus TCP	AP, WIFI, Ethernet	CAN / Modbus / Wi-Fi		
Charging Mode	Telescopic /	AGV contact	Telescopic / AGV contact		
Protection	OVP/OCP/Reverse	Polarity/Backflow	OVP / OCP / Reverse Polarity / Backflow		
Dimensions	Control: 264 ×	229 × 400 mm	Control: 351	× 215 × 447 mm	
Difficusions	Telescopic: 58	0×253×695 mm	Telescopic: 58	80 × 253 × 695 mm	
Net Weight	Control: 13 kg		Control: 23 kg		
Operating Temperature	-20°C t	o +65°C	-20°C to +65°C		
<b>Brush Plate Center Ground Clearance</b>	150mm -	Unlimited	150mm	- Unlimited	

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Our Wireless Charging Module offers a fully contactless power solution for industrial mobile robots such as AGVs and AMRs. Designed for high-efficiency energy transfer and long-term reliability, it enables automated charging in environments where contact-based systems are unsuitable.

#### **Key Features:**

- ▶ Inductive charging system with no mechanical wear or arcing
- ► High power transmission efficiency: ≥ 87-90%
- Modular integration: includes transmitter, receiver, and matched power supply
- Large alignment tolerance: ±50 mm (X), ±10 mm (Y), 10-80 mm (Z)
- Supports CAN or RS485 for system communication and monitoring

Model	AB-WLC-1200-48V	AB-WLC-3000-48V	AB-WLC1500-24V	AB-WLC3000-24V		
Power Adaptor Input	90-264 VAC	110-264 VAC	110-264 VAC	110-264 VAC		
Rated Power	1200 W	3000 W	1500 W	3000 W		
Output Voltage	40 - 60 VDC	40 - 60 VDC	20-30 VDC	21-30 VDC		
Output Current	0-20 A	50 ±1 A	50 A ±1 A	100 A ±1 A		
Efficiency	≥85%	≥87%	87%	85%		
Working Distance (Vertical)	10 - 40 mm	40 - 80 mm	40 - 50 mm	0 – 80 mm		
<b>Horizontal Offset Tolerance</b>	X: 20 mm / Y: 10 mm X: 50 mm / Y: 10 mm		X: 20 mm / Y: 10 mm	X: 50 mm / Y: 10 mm		
Communication	RS485	/ CAN	RS485 / CAN			
Cooling Method	Natural	cooling	Natural cooling			
Protection	Over-temp/over-voltage/ov	ver-current/Status Indicator	Over-temp/over-voltage/ov	ver-current/Status Indicator		
Transmitter Size	190 × 170 × 59 mm	300 × 300 × 80 mm	300 × 300 × 80 mm	300 × 300 × 80 mm		
Receiver Size	190 × 140 × 49 mm	250 × 250 × 70 mm	250 × 250 × 70 mm	300 × 300 × 116 mm		
Power Adaptor	294 × 210 × 111 mm	520 × 300 × 123 mm	520 × 300	× 123 mm		
Protection Rating (TX:Transmitter/RX:Receiver)	TX: IP65 RX: IP65 Power Supply Box: IP54		TX:   RX: Power Supp	IP65		
Operating Temperature	-40°C	to 60°C	-20°C to 50°C	-40°C to 60°C		

# Lithium-ion Battery series



**Key Features:** 

Our LiFePO<sub>4</sub> Battery Modules are built with high-grade lithium ironphosphate cells and a robust BMS, providing safe, efficient, and long-lasting power for industrial mobile robots such as AGVs and AMRs. Designed for demanding environments, these battery packs support modular expansion, fast charging, and advanced

- Offer superior energy density, allowing for longer operation times and reduced space requirements
- Engineered to deliver over 2000 charge and discharge cycles, ensuring durability and fewer replacements
- Equipped with advanced charging technology to minimize downtime and enhance operational efficiency
- Designed to perform reliably across a wide range of temperatures and environmental conditions

#### Realiable & Durable

- Stable Output, 24/7 Performance
- Safe & Long-Lasting for Every Move
- Strong Core Power, Uninterrupted Operation







### Modular Lithium-ion Battery

Capacity

approximately 1.1 kWh, available in 24 V 45 Ah or 48 V 23 Ah

Scalability

Stackable for flexible system expansion

Safety

BMS protection for over-temp/ over-voltage/over-current

Certifications

UL, CE, FCC, EN13849, UN 38.3

Model	AB-BT-LFP-24V-45AH-MOD	AB-BT-LFP-48V-23AH-MOD			
Nominal Voltage	24 V	48 V			
Nominal Capacity	45 Ah	23 Ah			
Max. Charging Current	40 A	23 A			
Max. Continuous Discharge	40 A	20 A			
Cycle Life	≥2000cycles	(@70%-80%)			
Communication	CA	Nopen			
Certifications	UL / CE / FC	C / EN13849 / UN38.3			
Dimensions (mm)	310×272×162	382×222×102			
Net Weight	13.3 kg 13.5 kg				
Operating Temperature	Charge:0-45°C /Discharge:-20-60°C				





### Customized Battery-LFP 24V

Customizable

24Ah/30Ah/50Ah/60Ah/100Ah/210Ah

Quality from Design

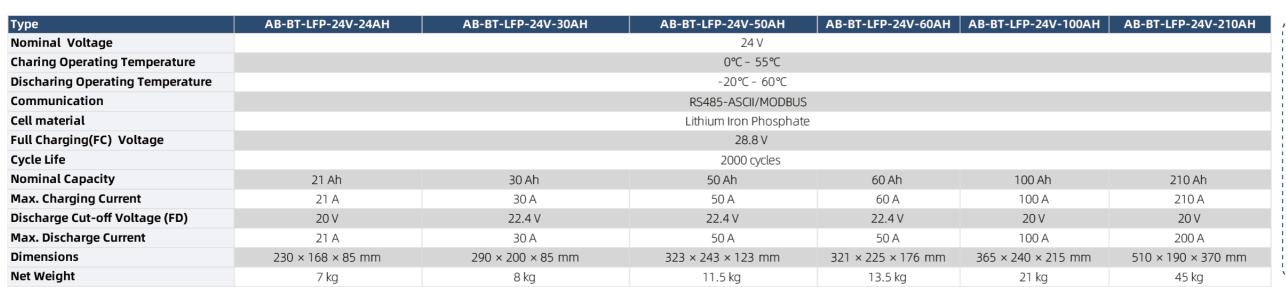
Quality Cells from BYD/CATL/Gotion, etc

Safety

**Built-in BMS protection** 

**BMS** Communication

RS485-ASCII/MODBUS





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### Customized Battery-LFP 48V

Туре	AB-BT-LFP-48V-9AH	AB-BT-LFP-48V-12AH	AB-BT-LFP-48V-20AH	AB-BT-LFP-48V-30AH	AB-BT-LFP-48V-30AH- Split	AB-BT-LFP-48V-30AH- Paralled	AB-BT-LFP-48V
Nominal Voltage			48	V			
Charing Operating Temperature			0°C-5	55°C			
Discharing Operating Temperature			-20°C-	60°C			
Communication			RS485-ASCII	/MODBUS			
Cell Material			Lithium Iron F	Phosphate			
Cycle Life			>2000 (	cycles			
Full Charging(FC) Voltage	54 V	57.6 V	54 V	54 V	54 V	54 V	54 V
Nominal Capacity	9 Ah	12 Ah	20 Ah	30 Ah	30 Ah	30 Ah	40 Ah
Max. Charging Current	10 A	24 A	20 A	30 A	30 A	30 A	40 A
Discharge Cut-off Voltage (FD)	37.5 V	40 V	37.5 V	37.5 V	37.5 V	37.5 V	37.5 V
Max. Discharge Current	10 A	24 A	40 A	30 A	30 A	30 A	40 A
Dimensions	200 × 150 × 80 mm	190 × 148 × 140 mm	295 × 99.5 × 220 mm	255 × 170 × 180 mm	200 × 155 × 130 mm	300 × 235 × 135 mm	310 × 250 × 137 mm
Net Weight	3 kg	8 kg	9 kg	12.5 kg	13 kg	13 kg	15 kg

Type	AB-BT-LFP-48V-54AH	AB-BT-LFP-48V-72AH	AB-BT-LFP-48V-100AH	AB-BT-LFP-48V-173AH	AB-BT-LFP-48V-300AH	AB-BT-LFP-48V-412AH
Nominal Voltage			48 V			
<b>Charing Operating Temperature</b>			0°C − 55°C			
Discharing Operating Temperature			-20°C - 60°C			
Communication	RS485-ASCII/MODBUS					
Cell Material	Lithium Iron Phosphate					
Cycle Life			>2000 cycles			
Full Charging(FC) Voltage	54 V	57.6 V	54 V	57.6 V	54 V	57.6 V
Nominal Capacity	54 Ah	72 Ah	100 Ah	173 Ah	300 Ah	412 Ah
Max. Charging Current	50 A	50 A	100 A	100 A	200 A	200 A
Discharge Cut-off Voltage (FD)	37.5 V	44.8 V	37.5 V	40 V	37.5 V	40 V
Max. Discharge Current	50 A	50 A	100 A	100 A	200 A	300 A
Dimensions	400 × 260 × 145 mm	430 × 235 × 230 mm	380 × 33 × 220 mm	680 × 300 × 240 mm	900 × 360 × 260 mm	850 × 550 × 275 mm
Net Weight	21.5 kg	32.5 kg	40 kg	65 kg	105 kg	200 kg

### • Low-temp. Battery

Cycle Life	Ty
2000+ cycles	N
	Cl
	Di
Efficiency	C
0-98% charging Efficienecy	C
	C
	F
Temp Range	N
-20°C to 60°C	M
	Di
	M
Customization	Di
24V, 48V, 9Ah to 412Ah Customizable	N

Туре	AB-BT-LTO-24V-10AH-LT	AB-BT-LTO-24V-60AH-LT	AB-BT-LTO-48V-10AH-LT
Nominal Voltage	24 V	24 V	48 V
Charing Operating Temperature		-30°C − 55°C	
Discharing Operating Temperature	-30°0	C − 60°C	-30°C−55°C
Communication		RS485-ASCII/MODBUS	
Cell Material	Lithium Iron Phosphate(LFP)		
Cycle Life	>2000 cycles		
Full Charging(FC) Voltage	28 V	28.8 V	56 V
Nominal Capacity	10 Ah	60 Ah	10 Ah
Max. Charging Current	40 A	50 A	40 A
Discharge Cut-off Voltage (FD)	17 V	16 V	34 V
Max. Discharge Current	10 A	50 A	10 A
Dimensions	225 × 100 × 170 mm	330 × 320 × 125 mm	260 × 140 × 170 mm
Net Weight	4 kg	18 kg	8 kg



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# DC-DC

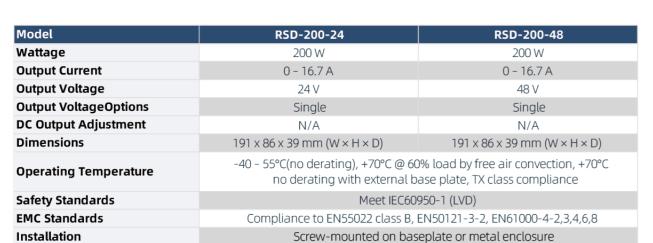
### DC-DC Enclosed 200W

Rated Power Wide Input Voltage

240W 2:1 wide input range

Output Voltage Safety Standard

24/48V EN50155 and EN45545-2 Railway Standard



#### • DC-DC DIN-Rail 240W

Rated Power Input Voltage Output Voltage Safety Standard

240W 14.4-154V 12/24/48V EN50155 Railway Standard

		W 40D-24
d	DOWN TO	2 1 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
	H CC	Θ° 200

Model	DDR-240-24 DDR-240-48		
Wattage	240 W	240 W	
Output Current	0-10 A	0-5 A	
Output Voltage	24 V	48 V	
<b>Output Voltage Options</b>	Single	Single	
DC output adjustment	24-28 V	48-56 V	
Dimensions	40 x 125.2 x 113.5 mm(W × H × D)	40 x 125.2 x 113.5 mm(W × H × D)	
Operating Temperature	Temperature -40-70°C		
Safety Standards	IEC 62368-1 (LVD, except for 67.2-154VIN) approved, EAC TP TC 004 approved; Design refer to UL508		
EMC Standards	Compliance to EN55032, EN61000-3-3. Compliance to EN55024, EN61000-6-2 (EN50082-2), EN61000-4-2,3,4,5,6,8. Compliance to EN45545-2 for fire protection; Meet EN50155 / IEC60571 including IEC61373 for shock & vibration EN50121-3-2 for EMC		
Installation	Vertical DIN rail mounting		

# Brush Plate

#### Brush Plate

High Current Capacity

Supports 35A to 100A

**Durable Construction** 

**Copper-carbon alloy electrodes** 

Compact & Efficient Design

40% compression rate for reliable contact

Robust Operating

Up to 50,000 charge cycles



Model	AB-BP35A	AB-BP50A	AB-BP100A	
Electrical Parameters				
Supported Current	35 A	50 A	100 A	
Supported Voltage		No Limitation		
Essential Parameters				
Material	Aluminum/c	opper/copper carbon/nick	kel plating	
Electrode		1-4P		
Plate Compression		40%		
Plate Dimensions (L*W*H)	170 × 65 × 15 mm	220 × 90 × 20 mm	220 × 90 × 20 mm	
Block Dimensions (L*W*H)	100 × 100 × 36 mm	120 × 100 × 30 mm	120 × 100 × 30 mm	
Net Weight	1.0 kg	1.5 kg	1.5 kg	
Duration		30000-50000 times		
Environmental Parameters				
Working Environment		Indoor		
Operating Temperature		-20°C − 45°C		
Storage Temperature	-25	-25°C − 60°C, Humidity 5 − 95%		
Atmospheric Pressure	86 kPa - 106 kPa			

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# **ATOMBOTIX**



### **Key Capabilities**



#### **Environment Perception**

Builds an accurate map of the surroundings, detects static and dynamic obstacles, and recognizes key environmental features.



#### Self-Localization & State Awareness

Continuously determines precise position, orientation, and movement status to support stable navigation.



#### Task Object Perception

Identifies, locates, and aligns with pallets, shelves, or other cargo to enable accurate loading and unloading.



#### Safety Perception

Monitors for people and hazards, dynamically adjusts speed, and triggers emergency stops to ensure safe operation.

Our Perception System enables intelligent, safe, and precise navigation for industrial mobile platforms such as AGVs and AMRs. Designed for dynamic environments, this suite integrates multiple sensors—ranging from magnetic detection to advanced LiDAR and vision modules—to support localization, obstacle avoidance, POI recognition, and operational safety.

# **2D Lidar Series**

We offer a high-performance 2D Time-of-Flight (TOF) LiDAR series—including Mini Navi Pro, 2D Navi Pro, Ranger, and Ranger Pro—engineered for AGV and AMR navigation, obstacle detection, and safety monitoring in factory and warehouse settings.

#### **Key Features:**

- Robust obstacle detection with configurable multi-echo and up to 64 detection channels
- Flexible field-of-view options ———— 270° or full 360° scanning for optimized coverage
- Exceptional resolution & accuracy angular resolution down to 0.018°, absolute accuracy ±20 mm
- Wide working range ——— up to 50 m for high-reflectivity targets; low-end sensitivity at 0.05 m
- High scanning frequency up to a maximum sampling rate of 600k, improving measurement accuracy and angular resolution



# 2D Lidar series





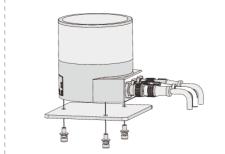




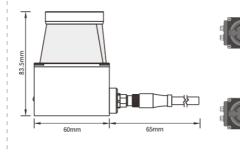


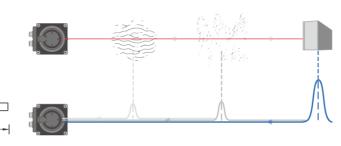
Model	2D NAVI PRO	MINI NAVI	MINI NAVI PRO	RANGER	RANGER PRO
Detection Range	0.05-20 m (2% reflectivity) 0.05-50 m (90% reflectivity)	0.05–10 m (10% reflectivity) 0.05–30 m (90% reflectivity)	0.05-10 m (10% reflectivity) 0.05-50 m (90% reflectivity)	0.05-2 m (10% reflectivity) 0.05-5 m (90% reflectivity)	0.05-6 m (10% reflectivity) 0.05-10 m (90% reflectivity)
Scanning Angle	360° (2D)	320° (2D)	360° (2D)	270° (2D)	270° (2D)
Sampling Rate	50kHz / 100kHz / 150kHz / 200kHz	432 kHz	540 kHz	74 kHz	74 kHz
Angular Resolution	Min. 0.018° (based on frequency, motor speed, sampling rate)	0.025° / 0.05° / 0.1° / 0.25° / 0.5° (depends on motor speed & frequency)	0.025°	0.1° / 0.2° (software configurable)	0.1° / 0.2° (software configurable)
Scan Frequency	10Hz, 15Hz, 20Hz, 25Hz, 30Hz	15 Hz, 30 Hz (customizable)	12.5 Hz / 25 Hz / 50 Hz	20 Hz	20 Hz
Accuracy	Measurement Accuracy ±20 mm Repeatability Accuracy ±10 mm Measurement Resolution 1 mm	Measurement Accuracy ±20 mm Repeatability Accuracy ±10 mm Measurement Resolution 1 mm Measurement Noise ±20 mm	Measurement Accuracy ±20 mm Repeatability <10 mm Measurement Noise ±20 mm Measurement Resolution 1 mm	Measurement Accuracy ±30 mm Measurement Noise ±30 mm	Measurement Accuracy ±30 mm Measurement Noise ±30 mm
Communication Interfaces	CANOpen, Ethernet, RS485, TCP/UDP	Ethernet, I/O	Ethernet, I/O, CAN	I/O, CAN, RS232, RS485, Ethernet, USB (Micro), TCP/UDP	I/O, RS232, RS485, CAN, USB, Ethernet
Digital Outputs	4 × NPN	4 × NPN	4×NPN	4×NPN	4 × NPN
Regional Protection Zones	3 zones	3 zones	3 zones	3 zones	3 zones
Obstacle Avoidance	64 channels (each with 3 detection ranges)	16 channels	16 channels	64 channels	64 channels
Indicator Lights	4 × LED (green, yellow, orange, red)	4 × LED (green, yellow, orange, red)	4 × LED (green, yellow, orange, red)	4 × LED (green, yellow, orange, red)	4 × LED (green, yellow, orange, red)
<b>Protection Rating</b>	IP65	IP65	IP65	IP65	IP65
Operating	-10°C to 50°C	-10°C to 50°C	-10°C to 50°C	-10°C to 50°C	-10°C to 50°C
Temperature	(indoor, no frost/condensation)	(indoor, no frost/condensation)	(indoor, no frost/condensation)	(indoor, no frost/condensation)	(indoor, no frost/condensation)

### Application Scenarios:









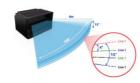




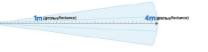












### 3D Lidar series

Our3D LiDAR Series, including 3D Ranger and Ranger Slim, delivers rich, high-resolution point-cloud sensing for advanced AGV and AMR navigation, dynamic obstacle detection, and environmental mapping. These compact sensors enable full spatial awareness in both structured and unstructured settings.

#### **Key Features:**

- Full 360° horizontal & up to 59° vertical scanning with 40 vertical scan lines
- Long detection range: up to 40 m at 10% reflectivity (- 70 m at 80%) with ≤ 2 cm accuracy at 10 m, and high close-range sensitivity down to 0.1 m
- ▶ High point-density output: ~200,000 points/sec (first return), 10 Hz frame rate standard
- Ultra-compact design:  $\sim$ 65 × 65 × 60 mm; lightweight 265 g; IP67-rated for rugged environments; self-heating for sub-zero operation
- ▶ Built-in IMU & synchronization: supports IEEE 1588 PTP, GPS timestamp, improved motion compensation

### • 3D Ranger

Range Beams 40m @10% Reflectivity 40

Angular Resolution Coverage

15 360° Horizontal & 59° V



Model	3D Ranger	
Detection Range	0.1-70 m (Reflectivity ≥10%)	
FOV	Horizontal: 360° Vertical: -7°-52°	
Beam	40 lines	
Sampling Rate	200,000 Hz	
Angular Precision (1σ)	< 0.15°	
Range Accuracy	≤ 2 cm	
Scan Frequency	10 Hz	
Laser Safety	Class 1	
Close Proximity Blind Zone	0.1 m	
Interface	Ethernet (100BASE-TX)	
IMU	Built-in IMU Model: ICM40609	
Power Supply	9-27 VDC, 6.5 W	
Protection Rating	IP67	
Dimensions	65 × 65 × 60 mm	
Operating Temperature	-20°C to 55°C	

### Ranger Slim

Range Angle Resolution

0.1° 4m

**Detection Angle** Obstacle Avoidance Channels

120°, 4-line scanning 64



Model	Ranger slim
Detection Range	0.05-1.5 m (10% reflectivity) 0.05-4.0 m (90% reflectivity)
FOV	120° (4 layers, 12° vertical span)
Beam	4 lines
Sampling Rate	144 kHz
Angle Resolution	0.5°
Absolute Accuracy	±40 mm
Scan Frequency	4×10 Hz
Laser Safety	Class 1
Channels	64 obstacle detection channels
Interfaces	I/O, USB, RS232, RS485, CAN, Ethernet
Status LEDs	Power (Green), Output 1-3 (Yellow/Orange/Red)
Power Supply	DC 18-30 V, <1.2 W
Protection Rating	IP65
Dimensions	70 × 51.5 × 40 mm
Operating Temperature	-10°C to 50°C (Indoor)

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# Camera

### Object Finder-HD

Frame Rate: Up to 24fps, 16fps @ 1280 x 960

24fps @ 640 x 480

Image Output

Depth, RGB, IR, point cloud images

Connectivity

M12 X-Code, 8-pin female connector, and Gigabit Ethernet

Durability

#### **IP65** protection

Model	Object Finder-HD
Technology	Stereo Vision + IR Laser
Depth Range	800-3000 mm (Adjustable via SGBM)
Near Field of View	850 mm x 710 mm @ 800 mm
Near Field of View	(H/V: Approximately 56°/48°)
Far Field of View	3465 mm x 2670 mm @ 3000 mm
rai rietu oi view	(H/V: Approximately 60°/48°)
Frame Rate (FPS) @	15 fps @ 1280 x 960
Resolution (Depth)	19 fps @ 640 x 480
Resolution (Deptil)	19 fps @ 320 x 240
	6 fps @ 2560 x 1920 @ CSI BAYER12GBRG
Frame Rate (FPS) @	4 fps @ 2560 x 1920 @ YUYV
Resolution @ Image	8 fps @ 1920 x 1440 @ YUYV
Format (Color)	16 fps @ 1280 x 960 @ YUYV
	25 fps @ 640 x 480 @ YUYV
Output	Depth Map, RGB, IR, Point Cloud
Trigger	2× Input/Output (Rising/Falling Edge)
Data Interface	Gigabit Ethernet (8-pin female)
Power Supply	DC 24V ±10%, 5W (idle) / 9W (active)
IP Ratings	IP65
Dimensions	145 × 35 × 90 mm
Net Weight	620 g
Operating Temperature	−10°C to 50°C

### Object Finder-iTof

Depth Resolution

Durability

640 x 480@15FPS

**IP65** protection

**RGB** Resolution

1600x1200@15fps

Output Format

16bit (Depth) + 8bit (IR) + JPEG (RGB)

Connectivity

#### **Gigabit Ethernet**

Model	Object Finder-iTof
Technology	Time-of-Flight (ToF) Depth Camera
Depth Range	0.15 - 5 m
Depth Resolution	640 × 480 @ 15 fps
&Frame rate	040 × 400 @ 151ps
RGB Resolution	1600 × 1200 @ 15 fps
&Frame Rate	1000 × 1200 @ 151ps
Depth Sensor FOV	H - 67° V - 50°
RGB Sensor FOV	H - 70° V - 50°
Output	16-bit Depth, 8-bit IR, JPEG RGB
Trigger	1× Digital Input (Passive Sync)
Data Interface	Gigabit Ethernet
Power Supply	PoE+/12V - 24V DC
IP Ratings	IP42
Dimensions	125 × 50 × 34.5 mm
Net Weight	256 g
Operating Temperature	-20°C to 50°C



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#### Perception

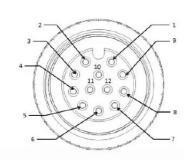
### **QR Scanning Camera**

This industrial-grade code reader is specifically designed for Automated Guided Vehicles (AGVs) and other intelligent logistics systems. With its robust hardware design and advanced decoding algorithms, it delivers reliable performance in challenging environments where barcodes may be dirty, damaged, or have low contrast. The device integrates seamlessly into automated workflows, offering fast and precise code reading, versatile connectivity, and optimized optical design. Its compact structure and durable build make it ideal for continuous operation in demanding industrial applications such as warehouse automation, production lines, and material handling systems.

#### **Key Features:**

- Exceptional algorithm performance, effectively handling barcode contamination, damage, and low-contrast conditions.
- Built-in decoding algorithm with high recognition rate and fast speed
- Supports saving, loading, and switching between multiple sets of user parameters
- ▶ Integrated aviation connector with rich I/O interfaces
- Equipped with M12 fixed-focus lens, supporting large field-of-view code reading and positioning









Model	QR Navigator
Focal Length	3.37 mm
Working Distance	100 mm
FOV	110 × 93 mm
Max. Reading Speed	125 codes/sec
FOV Angle	57.6° (H) × 49.9° (V)
Depth of Field	±20 mm
Frame Rate	120 fps
Sensor Type	CMOS, Global Shutter
Accuracy	0.1° / 0.1 mm
Interface	Ethernet (100 Mbps), RS485, I/O
Pixel Size	5.4 μm × 5.4 μm
Function	DM-12&DM-14, DM4x4
Weight	225 g
IP Ratings	IP65
Dimensions	60 × 60 × 43 mm

159 60 I

**POWER** 

**NET** 

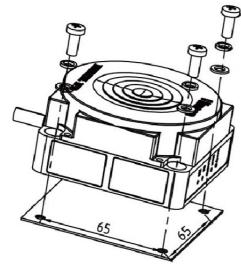
TRIG

**RUN** 

**ERR** 

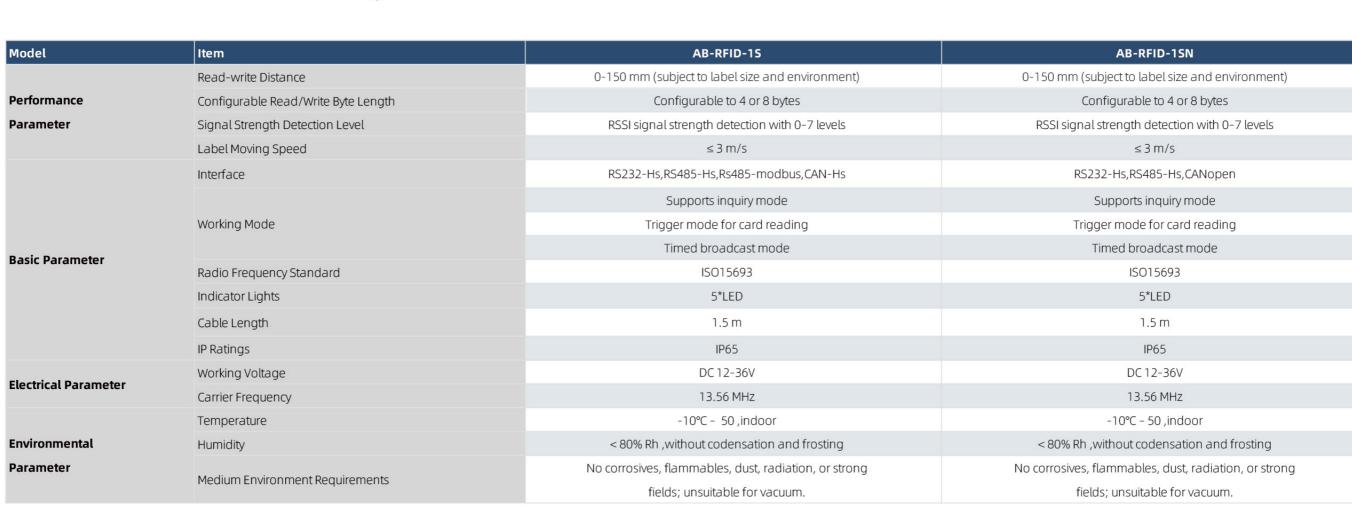
RFID

The AB-RFID-1S is a high-performance RFID reader tailored for industrial automation, including AGV (Automated Guided Vehicle) systems.









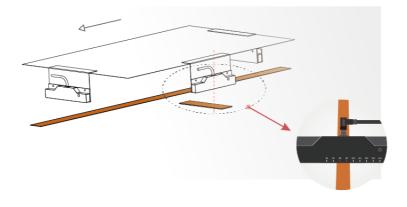
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#### Perception --

# Magnetic

### ◆ Magnetic Sensor-8/16/16pro

The AB-MGS Series high-precision magnetic navigation sensors offer a detection accuracy of 1 mm, making them especially suitable for high-precision magnetic strip navigation. By detecting the relative position of the magnetic field, they enable AGVs to achieve more accurate auxiliary positioning and docking, resulting in superior navigation, positioning, and parking precision.







Model	Item	AB-MGS-080N	AB-MGS-160N	AB-MGS-160ND	
	Detection Height	10-50 m	10-50 m	10-50 m	
	Detection Range	±70 mm	±75 mm	±75 mm	
	Detection Accuracy	3 mm	3 mm	1 mm	
	Number of Output Digital Quantity Points	16-bit digital output points	16-bit digital output points	16-bit digital output points	
<b>erformance</b> Distance between Detection Points		20 mm	10 mm	10 mm	
Parameter	Sensor Sensitivity	0-9 Levels (Configurable)	0-9 Levels (Configurable)	0-9 Levels (Configurable)	
	Induction Polarity	N-pole,S-pole,NS-pole (Configurable)	N-pole,S-pole,NS-pole (Configurable)	N-pole,S-pole,NS-pole (Configurable)	
	Detection Signal	N/S pole magnetic field signal	N/S pole magnetic field signal	N/S pole magnetic field signal	
	Detection Range of Magnetic Field Intensity	1.5 to 95 Gauss	1.5 to 95 Gauss	1.5 to 95 Gauss	
	Magnetic Strip Detections Number	3	3	3	
Electrical Parameter	Rated Voltage	24V ± 10%	24V ± 10%	24V ± 10%	
	Woriking Voltage	10 - 32V	10 - 32V	10 - 32V	
	Working Current	< 20mA (Typical Value)	< 20mA (Typical Value)	< 20mA (Typical Value)	
	Power	< 0.5W	< 0.5W	< 0.5W	
	Interface	RS232,RS485,Modbus,CAN	RS232,RS485,Modbus,CAN	RS232,RS485,I/O,CANOPEN	
	Magnetic Strip Position Deviation Data	Supported	Supported	\	
	Magnetic Field Strength Detection Data	Supported	Supported	\	
Basic Parameter	Position Output	Supported	Supported	Supported	
	Switch Signal Output	Supported	Supported	\	
	Strength Signal Output	Supported	Supported	Supported	
	Branch Selection Function	Supported (Left / Straight / Right commands)	Supported (Left / Straight / Right commands)	Supported (Left / Straight / Right commands)	
	LED	Red,Green	Red, Green	Red,Green	
	Cable Length	Standard: 1.5 meters (Optional: 3 meters, 6 meters)	Standard: 1.5 meters (Optional: 3 meters, 6 meters)	Optional	
	Housing Material	Aluminum alloy	Aluminum alloy	Aluminum alloy	
	Protection Class	IP65	IP65	IP65	
vironmental	Temperature	-10°C~50°C ,indoor	-10°C~50°C ,indoor	-10°C~50°C ,indoor	
rameter	Humidity	< 80% RH, non-condensing and frost-free	< 80% RH, non-condensing and frost-free	< 80% RH, non-condensing and frost-free	

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# Magnetic

### Magnetic Sensor Bar-16&32&48&64

The IP65 protection, low power consumption, and software-configurable sensitivity make this product ideal for precise navigation and positioning tasks.

Detection Span Detection Accuracy

640mm/480mm/320mm/160mm 1mm

Detection Height Detection Points

0 - 50mm 64/48/32/16 points



Model	Item	AB-MLS-160N	AB-MLS-320N	AB-MLS-480N	AB-MLS-640N	
	Detection Height	0 - 50mm (@ 90 Gauss magnetic stripe)	0 - 50mm (@ 90 Gauss magnetic stripe)	0 - 50mm (@ 90 Gauss magnetic stripe)	0 - 50mm (@ 90 Gauss magnetic stripe)	
	Detection Range	±75 mm	±155 mm	±235 mm	±315 mm	
	Detection Accuracy	1 mm	1 mm	1 mm	1 mm	
	Number of Detection Points	16	32	48	64	
	Distance between Detection Points	10 mm	10 mm	10 mm	10 mm	
Performance	Sensor Sensitivity	0-9 Levels (Configurable)	0-9 Levels (Configurable)	0-9 Levels (Configurable)	0-9 Levels (Configurable)	
Parameter	Induction Polarity	N-pole,S-pole,NS-pole (Configurable)	N-pole,S-pole,NS-pole (Configurable)	N-pole,S-pole,NS-pole (Configurable)	N-pole,S-pole,NS-pole (Configurable)	
	Detection Signal	N/S pole magnetic field signal	N/S pole magnetic field signal	N/S pole magnetic field signal	N/S pole magnetic field signal	
	Response Time	5 ms	5 ms	5 ms	5 ms	
	Basic Error	1 mm	1 mm	1 mm	1 mm	
	Detection Magnetic Field Strength Range	1.5-165 Gauss	1.5-165 Gauss	1.5-165 Gauss	1.5-165 Gauss	
	Number of Supported Magnetic Strips	3	3	3	3	
	Rated Voltage	24V ± 10%	24V ± 10%	24V ± 10%	24V ± 10%	
Electrical Parameter	Working Volatge	DC 12-36V	DC 12-36V	DC 12-36V	DC 12-36V	
Electrical Parameter	Working Current	Typical < 20 mA	Typical < 20 mA	Typical < 20 mA	Typical < 20 mA	
	Power	≤ 7W	≤ 7W	≤ 7W	≤ 7W	
	Interface	RS232,RS485,Modbus,CAN	RS232,RS485,Modbus,CAN	RS232,RS485,Modbus,CAN	RS232,RS485,Modbus,CAN	
	Recommended Magnetic Rail Specification	Width: 30/50 mm, Thickness: 1.2 mm	Width: 30/50 mm, Thickness: 1.2 mm	Width: 30/50 mm, Thickness: 1.2 mm	Width: 30/50 mm, Thickness: 1.2 mm	
	Recommended Magnetic Strip Specification	10-30mm in diameter	10-30mm in diameter	10-30mm in diameter	10-30mm in diameter	
	Magnetic Strip Position Deviation Data	Supported	Supported	Supported	Supported	
<b>Basic Parameter</b>	Magnetic Field Strength Detection Data	Supported	Supported	Supported	Supported	
	Position Output	Supported	Supported	Supported	Supported	
	Switch Signal Output	Supported (for switching value output only)	Supported (for switching value output only)	Supported (for switching value output only)	Supported (for switching value output only)	
	Track Selection Function	Supported (Left branch, Straight, Right branch	Supported (Left branch, Straight, Right branch	Supported (Left branch, Straight, Right branch	Supported (Left branch, Straight, Right	
	Township	commands)	commands)	commands)	branch commands)	
Environmental	Temperature	-10°C - 50°C ,indoor	-10°C - 50°C ,indoor	-10°C - 50°C ,indoor	-10°C - 50°C ,indoor	
Parameter	Humidity	< 80% RH, non-condensing and frost-free	< 80% RH, non-condensing and frost-free	< 80% RH, non-condensing and frost-free	< 80% RH, non-condensing and frost-free	
	Background Magnetic Field	< 1 Gauss	< 1 Gauss	< 1Gauss	< 1 Gauss	

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#### ◆ AB-MC-IPC

The High-Performance Embedded Intelligent Controller features a modular design with integrated high-performance CPU and GPU, supporting artificial intelligence (AI) computing. Specifically engineered for AGV (Automated Guided Vehicle) and AMR (Autonomous Mobile Robot) systems, its fanless structure and compact, robust enclosure make it ideal for high-load industrial applications.

#### **Key Features**



#### Modular CPU Design

Supports Intel 11th Gen Core i7/i5 and Celeron J1900 processors, catering to different performance requirements.



#### Extensive I/O Interfaces

Offers up to 4 Ethernet ports, 6 serial ports (RS232/RS485), 16-channel digital I/O (DIO), CAN bus, GPIO, and supports EtherCAT bus motion control.



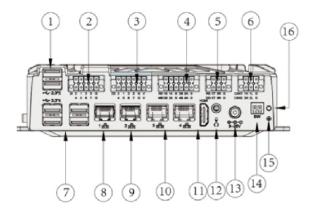
#### Flexible Storage Options

Accommodates 2.5" SATA III HDD/SSD and M.2 SSD with customizable capacity for large-scale data storage.



#### Wireless Networking

Supports 4G, Wi-Fi, and Bluetooth, enabling easy device connectivity and data transmission.



① USB 2.0\*2

② 8-Channel Digital Input

(I) LAN3 + LAN4 (Optional)

3 8-Channel Digital Output4 PS484 1/2/3/4

① HDMI ② Mic + Line out

⑤ RS232 5/6

13 +9 - 28V DC IN

Remote switch/
Physical switch

⑥ CAN 1/2⑦ USB3.0 \*4

® USB3.0 \*4

(Optional)



Model	AB-MC-IPC-M20-I5	AB-MC-IPC-M20-I7			
Operating System	Linux Ubuntu (Windows Opt	tional, with separate License )			
	Processor: Intel <sup>@</sup> 11 <sup>th</sup> Core <sup>TM</sup> i5 1135G7 2.4GHz,	Processor: Intel <sup>®</sup> 11 <sup>th</sup> Core <sup>TM</sup> i7 1165G7 2.8GHz,			
	UP to 4.2GHz, 8M Cache, TDP 12-28W	UP to 4.7GHz, 12M Cache, TDP 12-28W			
System Performance	Memory: Supports DDR4 3200 MHz, up to 32 GB	Memory: Supports DDR4 3200 MHz, up to 32 GB			
	(single memory slot)	(single memory slot)			
	Storage: 1×2.5" SATAIII HDD&SSD+M.2(2242 SATA)				
Graphic	Intel Iris Xe Graphics, DirectX12.1, OpenGL 4.6,	.1 x HDMI, resolution 4096*2304@60Hz			
	Network:				
	LAN1/2: Intel i211 10/100/1000Mbps, supports Wake-on-LAN				
	LAN1/2/3/4: Intel i210 10/100/1000Mbps, S				
	wake up.(Optional)				
Interface	Optional: 3 x COM, 6 x COM, 10 x C	OM(COM 1/2 - 3 kV optical isolation,			
	configurable via BIOS for RS-232/485; COM 3 to COM 10: RS-232)				
	USB: 4 x USB3.0, 2 x USB2.0				
	Others: 1 x Mic-in, 1 x Line-out, 1 x HDMI				
	DI/DO: 8 x DI, 8 x DO				
W-b		oorts Overvoltage and			
Voltage	Reverse polarity Protection)				
Power Consumption	Maximum power consumption 65W				
rower consumption	(i7 1165G7 CPU/8G Memory)				
Cooling Method	·	m integrated heat dissipation			
_		issipation (i5 and above)			
Installation	3	Rail Mounting/Wall Mounting			
Dimensions	·	ength*width*height)			
		patibility: IEC60068-2-64			
	_	-20 - 50°C (optional SSD), (2.5″ HDD)			
Environment		rature: -30 - 70°C			
	·	Francisco - 70 C			
	Random vibration 5-500HZ, half an hour per axis				
Net Weight		2 kg			
_		attery, can work continuously for			
Backup UPS		at 25°C ambient temperature)			
Network Modem	·	ifi/4G LTE/5G)			
		,			

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### **ATOMBOTIX**

# **Other Components**

To ensure safe, efficient, and reliable operation of Automated Guided Vehicles (AGVs), a wide range of auxiliary components are required. These "Other Components" serve critical roles in enhancing system performance, improving human-machine interaction, and ensuring workplace safety. At ATOMBOTIX, we offer a comprehensive selection of peripheral products designed for industrial-grade AGV platforms.



#### ▶ Why Safety Matters in AGV Systems



#### **Protecting People**

- Prevents accidents and injuries in workplaces shared by humans and AGVs.
- Safety devices (bumpers, warning lights, audio alarms) act as the first line of defense.



#### **Protecting Assets and Goods**

- Avoids costly collisions that can damage AGVs, cargo, and infrastructure.
- Reduces maintenance expenses and prolongs equipment lifetime.



#### **Enhancing Efficiency**

- Minimizes unplanned stops and downtime.
- Improves workflow with clear audio-visual warnings and network monitoring.



#### **Compliance and Standards**

- Meets international safety regulations such as ISO 3691-4 and CE certification.
- Ensures AGVs are legally deployable in global markets.



#### Audio



#### Application:

Used in AGVs to provide audible alerts during start-up, movement, or fault conditions, ensuring safety in busy industrial environments.

#### • Function:

Generates sound signals to warn nearby personnel of AGV status changes, reducing collision risks and enhancing workplace awareness.

Model Power Dimensions Working Voltage Shell Material

AB-AD100-5 W 8Ω5 W 100 × 100 × 33.5 mm DC 5 V Aluminium Alloy





### Bumper

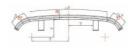


- Application:
- Installed on AGV body edges as a primary physical safety mechanism to prevent collisions.
- Function:

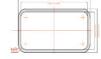
Immediately triggers an emergency stop when contact is made with a person or obstacle, ensuring operator and equipment safety.

Triggering Force Value Trigger Distance **Sheating Material** Hits

AB-BS-RC-Lxxx 8-25 N 2-5 mm **EPDM** 20.000 times

















### **ATOMBOTIX**

#### ◆ LED 🥌

Application:

Provides visual signals to indicate AGV operating status, battery level, or error messages.

• Function:

Communicates AGV conditions through color-coded lights or digital display, enabling operators to quickly assess system state.

Model Single Section Length Communication Interface Blinking Order

AB LED01 100 mm RS485 **Fault Priority** SD/DMX controller







### Warning Light

Controller System



Application:

Mounted on AGVs for 360° visual warnings, improving safety in areas with heavy traffic and limited visibility.

• Function:

Emits bright flashing or rotating light signals to indicate AGV movement, emergency stop, or system fault.

Model Power Working Voltage Shape Cycle Time

Warning Light Series 18-30 W DC 12-80 V Dot/Arrow/Arc/Bar 30,000 hs



### Network

• Application:

Provides wireless or wired communication capability for AGVs to connect with central control systems or other vehicles.

• Function: Enables real-time data transmission for navigation, task scheduling, and fleet coordination.

Model Working Temp **Industrial Protection** Supported Bandwidth **Industrial Port** 

TL-CPE1300D -40 °C − 75 °C IEC/EN 61000-4 2.4G, 5G AC1300 DB9







### **Mobile Robot Retrofitting**

Our Retrofitting & Refurbishing Service helps you transform aging or manual industrial vehicles—such as forklifts, pallet trucks, and towing tractors—into fully autonomous AGVs equipped with modern navigation, safety, and fleet-management software tools.



#### WHY RETROFIT

- High cost of new AGVs
- Brown field space
- System integration pain

#### **Our Solution**

Retrofit fleet to save CapEx

Flexible Navigation & 3D safety systems
 API library & Workflow integration

#### Control System Upgrade

Replace or optimize controllers, motion systems, and drive units for higher precision and smoother path planning.

#### Navigation & Positioning Optimization

Upgrade to laser SLAM or hybrid navigation for greater adaptability.

#### Enhanced Safety Systems

Add or replace 2D/3D LiDAR, obstacle detection sensors, and safety PLCs for safe human-robot collaboration.

#### Power & Endurance Improvement

High-performance batteries, BMS, and charging systems with fast/auto-charging support.

### **Mobile Robot Retrofitting**

#### **▶** Support Vehicle Types:

We provide retrofit solutions for a broad spectrum of industrial vehicles — from forklifts, reach trucks, and pallet movers to cranes, yard tractors, and specialized material handling equipment.

#### **Legacy AGV Compatibility**

Retrofit solutions for both legacy AGVs and manually operated vehicles to enable automation.

#### **Modular Upgrades**

Flexible, workflow-specific modules tailored to different factory layouts and operational needs.





Electric forklifts & pallet tucks



Material Transport ACV



Heavy Duty AGVs



Delivery Robot

### Why Choose Us

We provide end-to-end retrofit expertise, from core technology to on-site execution



Mature centralized controller & software stack



Extensive experience in non-standard AMR retrofitting



On-demand local implementation support



Efficient Supply Chain, Short lead time

### Fast, flexible, and scalable AGV solutiontailored to you



#### Solution ·----

### **Customized Robot Building**

Fast (30-90 day) delivery of modular, application-specific AGVs — no vendor lock-in, open architecture, and cost-effective supply chain from China.

#### ► From AGV/AMR to More: Flexible Customization Services



Outdoor Robot



Cleaning Robot



Mobile Manipulator

# Semiconductor

ISO/GMP compliant design Logistics

Food

Pharmaceutical

### **▶ Industries We Serve**

We deliver AGV and AMR solutions across diverse industries, adapting to each sector's unique needs. From high-volume logistics to precision manufacturing and public services, we ensure seamless integration, reliable performance, and strong ROI.

10+

supported industrial protocols

5+

industry-specific robot designs delivered

<2 week

on-site deployment to production









### **ATOMBOTIX**

Complete plug-and-play for rapid AGV upgrades

### Mobile Robot Kit

Pre-configured kit with all essential hardware and software, allowing customers to build fully functional AGVs in-house with minimal setup









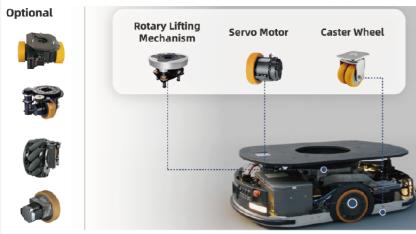
#### ► Versatile AGV Development Platform

Supports multiple chassis designs, navigation methods, and payload configurations, enabling rapid prototyping and scaling from pilot units to full production in diverse industrial environments

#### ► What Makes Our Kit Different









### ► Curious how our kit delivers true plug-and-play AGV building?

Here's a real example: the complete component list for a 600 kg payload AGV

Formfactor: Platform lifter with rotary lifting pad;

Kinematic: Differential Drive; Max Payload Capacity: 600kg ±

Retad Speed: 2.14m/s Operating Hours: 8 hr ±;

Contact Charging (Wireless Optional);AI: Rack leg recognition, Obastacle Avoidence;



Note: If targeting EU & US markets, functional safety design is advised. Please consult your account manager for details.						
Category	Part No.	Item	Note	Photo	Qty.	
Main Control	AB-MC-IPC-M20-IX	Main Controller	Localization & Navigation , Kinematic Control, Motion Planing , Sensor Processing , Object Recognition , Open API, Behavior Programming		1	
Perception	AB-LD-B01-R50-DRJ45	Lidar	For Localization & Obastacle Detection	-	2	
	AB-DaBai DCW 2	3D camera	For Spacial Obastacle Detection 3D ranger optional		2	
	AB-BS-XXXX(Customized)	Pressure Sensor Strip	Pressure Sensor Strip for front & back as last level safety		Customized	
Motion	AB-SJX-4680-400-48-50-1000	Lifting Mechanism	Module with Rotation Mechanism & Spiral Lifting Structure - For Light and Medium-duty Lifting		1	
	iWMC10411-04023-A180-MBDT	Integrated Servo Drive Wheel Assembly	As a travel motor, it performs motion functions and is responsible for the vehicle's driving and steering		2	
	AB-FW-D106-C300	Universal Wheel	Caster Wheel for support		4	
Network	TL-CPE1300D	Wireless Modem	Industrial Modem for Wifi		1	
Energy	AB-BT-LFP-48V-23AH-MOD	Battery	BMS Included/CAN/RS485		1	
	AB-WC-Brush	Charging Connector Terminal	Charging Brush	2.4	1	
	AB-DC-DDR-120C-24	DC-DC	Step down voltage to 24V for 24V-rated device power supply		1	
	AB-HD1200WP LP24	Manual Charger	Manual Charger-1200W	-	1	
	AB-CC-48V50A-YTSK	Auto Charging Station	Automatic Charger	**	1	
	ABLS-XXXX(Customized)	LED Strip	LED strip for the Robot Status: Operation Status, Turning Signal etc.		4	
	ABS5W02	Internal Magnetic Speaker	Speaker for Robot Status and warning	•	1	
Pheripharal	XB2BA55C	Buttons	Robot Switch & Reset		2	
	XB2BS542C	E-stop	Front, Back & Sides		3	
	AB-AS-2P-250A	Air Switch	Master switch, Protect the vehicle's electrical system from overcurrents and short circuits	1	1	
	AB-RE-48V-8PIN	Relay	Control for charging interface(wireless & contact charging)		1	
	AB-TB-XX	Terminal Block	Improved electrical wiring & cable management		Optional	
	7.0 inches HMI	НМІ	Provide interface visualization design, real-time status monitoring, and fault diagnosis & alarm functions.	-	1	
	AB-CCR-48V-100A	Charging Connector	The module is suitable for charging interfaces with manual charging mode	-	1	

- Throughout this solution, we've explored the tools, strategies, and insights that empower your automation journey. By combining cutting-edge technology with practical guidance, we aim to simplify complex processes and unlock new opportunities. By embracing innovation, we can achieve lasting impact.
- Let's drive the future of automation, together.